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A cutting guide positioner robot to improve bone-cutting precision in knee osteotomy

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BRIGIT Surgical Robot

BRIGIT (Bone Resection Instrument Guidance by Intelligent Telemanipulator), is a surgical robot used for optimal positioning of a guide providing mechanical support for a saw or a drill. BRIGIT is a compact 6 degree-of-freedom robot mounted onto a wheeled trolley, together with its control software.

Adequate position of the guide is derived from threedimensional calculations performed from desired surgical planning parameters and spatial position of anatomical landmarks. Pinpoint collection of anatomical landmarks is carried out with BRIGIT surgical robot and its pointing end effector device.

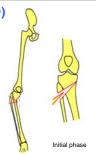
The study presented is carried out with dry bones and a prototype version of BRIGIT.



High Tibial Osteotomy (HTO)

HTO is a corrective surgical procedure in which the upper part of the tibia is resected with a precise angle so that the lower limb can be realigned, in order to change the biomechanics of the joint.

One of the major difficulties with HTO lies in the risks of over- or undercorrection leading to esthetic and functional complications.







Steps of the BRIGIT HTO technique



BRIGIT robot is used in a « cooperative



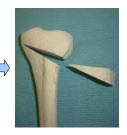
OSTEOTOMY



The cutting guide now replaces the pointing device. BRIGIT surgical robot precisely positions this cutting guide where the upper resection should be done.



Once the saw cutting is completed, BRIGIT now moves the cutting guide to the position where the second resection should be done.



The bone wedge is removed, measured and compared with the desired correction input to the system.

Results

mode » with its pointing device.

Results of the study are very encouraging with an average precision better than 0.7°

Advantages of BRIGIT assisted High Tibial Osteotomy

- Optimal precision in angle of correction
- No plane-oblique effect
- No per-op X-ray irradiation due to cut positionning
- Short and predictable procedure duration
- Easy and intuitive technique without navigation required