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# Free compact 2-categories 

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#### Abstract

Before one can attach a meaning to a sentence, one must distinguish different ways of parsing it. When analyzing a language with pregroup grammars, we are thus led to replace the free pregroup by a free compact strict monoidal category. Since a strict monoidal category is a 2 -category with one 0 -cell, we investigate the free compact 2 -category generated by a given category, and we describe its 2 -cells as labeled transition systems. In particular, we obtain a decision procedure for the equality of 2 -cells in the free compact 2 -category.


Keywords: compact 2-categories, non-symmetric monoidal categories, normalization, compact bilinear logic, categorial grammars, pregroup grammars

## 1 Introduction

An algebraic notion that has recently been applied in mathematical and computational linguistics is that of a pregroup [Lambek 99], a partially ordered monoid in which each element $a$ has both a left adjoint $a^{\ell}$ and a right adjoint $a^{r}$, such that

$$
a^{\ell} a \longrightarrow 1 \longrightarrow a^{\ell} a, a a^{r} \longrightarrow 1 \longrightarrow a^{r} a,
$$

where the arrow denotes the partial order.
As a first approximation one has recourse to the free pregroup generated by a partially ordered set of basic types. For example, look at the following English phrases:

$$
\begin{gathered}
\text { men and women } \\
\mathbf{p} \mathbf{p}^{r} \mathbf{p p}^{\ell} \mathbf{p} \\
\text { women whom I liked } \\
\mathbf{p} \mathbf{p}^{r} \mathbf{p o}^{\ell \ell} \mathbf{s}^{\ell} \pi_{1} \pi^{r} \mathbf{s}_{\mathbf{2}} \mathbf{o}^{\ell} \\
\mathbf{p} \mathbf{p}^{r}{\mathbf{p} \mathbf{o}^{\ell \ell}}^{\mathbf{s}^{\ell} \pi_{1} \pi^{r}} \mathbf{s}_{2} \mathbf{o}^{\ell}
\end{gathered}
$$

Here we have employed the following basic types:
$\pi_{1} \quad$ first person subject
$\pi \quad$ subject when the person does not matter
$\mathrm{s}_{2} \quad$ sentence in the past tense
s sentence when tense does not matter
p plural noun phrase.
We also postulate

$$
\mathbf{s}_{2} \longrightarrow \mathbf{s}, \pi_{1} \longrightarrow \pi
$$

to determine the partial order among basic types, so that e.g.

$$
\pi_{1} \pi^{r} \longrightarrow \pi \pi^{r} \longrightarrow 1, \mathbf{s}^{\ell} \mathbf{s}_{2} \longrightarrow \mathbf{s}^{\ell} \mathbf{s} \longrightarrow 1
$$

Note that we have assigned to each English word a type, namely a string of simple types of the form $\cdots \mathbf{a}^{\ell \ell}, \mathbf{a}^{\ell}$, $\mathbf{a}, \mathbf{a}^{r}, \mathbf{a}^{r r} \cdots$ where $\mathbf{a}$ is any basic type. In the above example, men, women, have been assigned basic types whereas

$$
\begin{aligned}
& \text { liked: } \quad \pi^{r} \mathbf{s}_{2} \mathbf{o}^{\ell} \\
& \text { and: } \mathbf{p}^{r} \mathbf{p p}^{\ell} \\
& \text { whom: } \quad \mathbf{p}^{r} \mathbf{p o}^{\ell \ell} \mathbf{s}^{\ell} .
\end{aligned}
$$

Then


These two derivations have evidently different meanings. This suggests that we should take the arrow to denote not just derivability, but the actual derivation. In other words, we should adopt the categorical imperative: replace partially ordered sets by categories. There are two distinct derivations

$$
\mathbf{p} \mathbf{p}^{r} \mathbf{p} \mathbf{p}^{\ell} \mathbf{p} \mathbf{p}^{r} \mathbf{p} \longrightarrow \mathbf{p}
$$

which might be thought of as morphisms in a certain category, or even, as we shall see, as 2-cells in a 2-category. Adjoints are usually defined in the 2-category of all (small) categories, but the same definition works in any 2-category. A 2-category is said to be compact, if every 1-cell has both a left and a right adjoint.

Our interest thus shifts to compact 2-categories (originally with one 0-cell) generated by a given partially ordered set. We may as well replace this partially ordered set by a category and we will ultimately abandon the assumption that there is only one 0 -cell. Thus, we aim to study the free compact 2 -category generated by a given category (or a given 2 -graph).

Let the reader be reminded that a 2 -category with one 0 -cell is usually called a strict monoidal category. To start with, we will construct a compact one, the category of transitions, and show that it is equivalent to the freely generated compact strict monoidal category. The 2-cells of the category of transitions are described as what is known in computer science as labeled transition systems. Horizontal composition models parallelism, vertical composition models temporal composition of transition systems [Eilenberg]. Our transitions systems are given in normal form, i.e. they have initial and final, but no intermediary states. Otherwise said, the 2-cells can be generated without vertical composition. The fact that every 2 -cell is equal to a 2 -cell in normal form is the categorical version of what logicians call "cut-elimination". Our proof of this fact also provides a decision procedure for the equational theory of compact 2-categories.

## 2 2-categories recalled

To remind the reader of the concept of a 2-category, let her recall the notion of a natural transformation $t: F \longrightarrow G$ between functors $F: \mathbf{M} \longrightarrow \mathbf{Q}, G: \mathbf{M} \longrightarrow \mathbf{Q}$. Here the categories $\mathbf{M}$ and $\mathbf{Q}$ are the 0-cells, $F$ and $G$ the 1-cells and $t$ is a 2-cell. The usual definition of natural transformations
requires the commutativity of the following diagram, where $f: A \longrightarrow B$ is a given arrow in the category M:

that is the equality

$$
\begin{equation*}
t B \circ F f=G f \circ t A=t f, \text { for } f: A \longrightarrow B, t: F \longrightarrow G, \tag{2.1}
\end{equation*}
$$

where $\circ$ denotes the composition of 2 -cells. It is reasonable to denote the diagonal by $t f$.
Now this equality remains valid if $A$ and $B$ are themselves 1-cells, say functors $\mathbf{N} \longrightarrow \mathbf{M}$, and then $t f$ denotes horizontal composition $t f: F A \longrightarrow G B$ as illustrated by the diagram:


This horizontal composition is to be distinguished from the vertical composition

$$
s \circ t: F \xrightarrow{t} G \xrightarrow{s} H,
$$

the usual composition of 2-cells. The two compositions are related by the equation

$$
\begin{equation*}
(s \circ t)(g \circ f)=s g \circ t f \tag{2.2}
\end{equation*}
$$

Mac Lane's so-called interchange law [Mac Lane].


If we identify $B$ with $1_{B}$ and $F$ with $1_{F}$, we see that (2.1) is a special case of (2.2). But (2.2) can also be deduced from (2.1) and the distributive laws

$$
\begin{equation*}
(s \circ t) C=s C \circ t C, F(g \circ f)=F g \circ F f \tag{2.3}
\end{equation*}
$$

as may be verified by diagram chasing.
As a consequence of (2.1), note that

$$
\begin{equation*}
1_{F A}=1_{F} 1_{A}=1_{F} A \circ F 1_{A}=F 1_{A} \circ 1_{F} A \tag{2.4}
\end{equation*}
$$

Identifying (the 2-cell) $1_{F}$ with (the 1-cell) $F$, (2.4) becomes

$$
\begin{equation*}
F A \circ F A=F A \tag{2.5}
\end{equation*}
$$

and, in the case where $A$ is an identity for horizontal composition, $F \circ F=F$. In the particular case where $f$ is the identity of the 1 -cell $A,(2.2)$ becomes

$$
\begin{equation*}
(s \circ t) g=(s \circ t)\left(g \circ 1_{A}\right)=s g \circ t 1_{A}=s g \circ t A . \tag{2.6}
\end{equation*}
$$

Finally, for $F: M \longrightarrow M, G: M \longrightarrow M, u: F \longrightarrow 1_{M}$ and $o: 1_{M} \longrightarrow G$

$$
\begin{equation*}
u o=o u \tag{2.7}
\end{equation*}
$$

Indeed, let 1 stand for $1_{1}{ }_{\mathbf{M}}$ and 1 for $1_{\mathbf{M}}$. Then

$$
o u=(o \circ \mathbf{1})(\mathbf{1} \circ u)=o \mathbf{1} \circ \mathbf{1} u=o \circ u
$$


and similarly,

$$
u o=(\mathbf{1} \circ u)(o \circ \mathbf{1})=\mathbf{1} o \circ u \mathbf{1}=o \circ u
$$


using (2.2) and $\mathbf{1} f=f=f \mathbf{1}$.

## 3 Adjoints in 2-categories

A 1-cell $G$ is said to be a right adjoint of 1-cell $F$, or $F$ a left adjoint of $G$, if there are 2-cells $\varepsilon: F G \longrightarrow 1$ and $\eta: 1 \longrightarrow G F$ such that

$$
\begin{array}{ll}
G \varepsilon \circ \eta G=1_{G}, & \varepsilon F \circ F \eta_{G}=1_{F} \\
G \leftarrow G F G \leftarrow G, & F \leftarrow F G F \leftarrow F,
\end{array}
$$

or, identifying $1_{G}$ with $G$,

$$
G \varepsilon_{G} \circ \eta G=G, \quad \varepsilon F \circ F \eta=F .
$$

As in linguistic applications, it may be useful to call the co-unit of the adjunction $\varepsilon$ a contraction and the unit $\eta$ an expansion and paraphrase the equations above by saying that an expansion is canceled by a contraction immediately following it.

All the usual properties of adjoints, familiar from the category of (small) categories remain valid in any 2 -category. For example, adjoints are unique up to isomorphism (see e.g. [2]). This implies in particular that one can choose canonical representatives

$$
G^{\ell}=F, \varepsilon_{G}: G^{\ell} G \longrightarrow 1, \eta_{G}: 1 \longrightarrow G G^{\ell}
$$

such that

$$
\begin{array}{ll}
G \varepsilon_{G} \circ \eta_{G} G=1_{G}, & \varepsilon_{G} G^{\ell} \circ G^{\ell} \eta_{G}=1_{G^{\ell}} \\
G \leftarrow G G^{\ell} G \leftarrow G, & G^{\ell} \leftarrow G^{\ell} G G^{\ell} \leftarrow G^{\ell} . \tag{3.1}
\end{array}
$$

Then $G^{\ell r} \cong G \cong G^{r \ell}$ and in the category $\mathrm{T}(\mathcal{C})$ described in Section 4, these isomorphisms are replaced by the equalities

$$
\begin{equation*}
G^{\ell r}=G=G^{r \ell} \tag{3.2}
\end{equation*}
$$

Note that if $H$ has a left adjoint $H^{\ell}$ with counit $\varepsilon_{H}$ and unit $\eta_{H}$, then $G H$ has a left adjoint $H^{\ell} G^{\ell}$ with counit $\varepsilon_{G H}$ and unit $\eta_{G H}$ given by

$$
\begin{equation*}
\varepsilon_{G H}=\varepsilon_{H} \circ H^{\ell} \varepsilon_{G} H, \eta_{G H}=G \eta_{H} G^{\ell} \circ \eta_{G} \tag{3.3}
\end{equation*}
$$

Indeed, by (2.1) the diagram below commutes

and therefore

$$
\begin{aligned}
G H \varepsilon_{G H} \circ \eta_{G H} G H & =G H \varepsilon_{H} \circ G H H^{\ell} \varepsilon_{G} H \circ G \eta_{H} G^{\ell} G H \circ \eta_{G} G H \\
& =G H \varepsilon_{H} \circ G\left(H H^{\ell} \varepsilon_{G} \circ G \eta_{H} G^{\ell} G\right) H \circ \eta_{G} G H \\
& =G H \varepsilon_{H} \circ G\left(\eta_{H} \circ \varepsilon_{G}\right) H \circ \eta_{G} G H \\
& =G\left(H \varepsilon_{H} \circ \eta_{H} H\right) \circ\left(G \varepsilon_{G} \circ \eta_{G} G\right) H \\
& =G H \circ G H=G H, \text { by }(2.5) .
\end{aligned}
$$

Similarly, $\varepsilon_{G H} H^{\ell} G^{\ell} \circ H^{\ell} G^{\ell} \eta_{G H}=H^{\ell} G^{\ell}$.
In particular, it follows that we may take

$$
\begin{equation*}
(G H)^{\ell}=H^{\ell} G^{\ell} \text { and }(G H)^{r}=H^{r} G^{r} \tag{3.4}
\end{equation*}
$$

For any 2-cell $f: F \longrightarrow G$, one can define a 2-cell $f^{\ell}: G^{\ell} \longrightarrow F^{\ell}$ as follows:

$$
\begin{equation*}
f^{\ell}=\varepsilon_{G} F^{\ell} \circ G^{\ell} f F^{\ell} \circ G^{\ell} \eta_{F} \tag{3.5}
\end{equation*}
$$

where on the right hand side, read from right to left, the arrows are

$$
F^{\ell} \leftarrow G^{\ell} G F^{\ell} \leftarrow G^{\ell} F F^{\ell} \leftarrow G^{\ell}
$$

We note that $f^{\ell}: G^{\ell} \longrightarrow F^{\ell}$ is the unique 2-cell which makes the following square commute:


Indeed, introducing the name generalized contraction for the diagonal $\varepsilon_{f}$ we show

$$
\begin{equation*}
\varepsilon_{f}=\varepsilon_{G} \circ G^{\ell} f=\varepsilon_{F} \circ f^{\ell} F \tag{3.6}
\end{equation*}
$$

as follows:

$$
\begin{aligned}
\varepsilon_{F} \circ f^{\ell} F & =\varepsilon_{F} \circ\left(\varepsilon_{G} F^{\ell} \circ G^{\ell} f F^{\ell} \circ G^{\ell} \eta_{F}\right) F \\
& =\varepsilon_{F} \circ\left(\varepsilon_{G} \circ G^{\ell} f\right) F^{\ell} F \circ G^{\ell} \eta_{F} F \\
& =\left(\varepsilon_{G} \circ G^{\ell} f\right) \circ G^{\ell} F \varepsilon_{F} \circ G^{\ell} \eta_{F} F, \text { by }(2.1) \\
& =\varepsilon_{G} \circ G^{\ell} f \circ G^{\ell}\left(F \varepsilon_{F} \circ \eta_{F} F\right) \\
& =\varepsilon_{G} \circ G^{\ell} f \circ G^{\ell} F \\
& =\varepsilon_{G} \circ G^{\ell} f .
\end{aligned}
$$

To show uniqueness, i.e.

$$
\begin{equation*}
\text { If } g: G^{\ell} \longrightarrow F^{\ell} \text { satisfies } \varepsilon_{G} \circ G^{\ell} f=\varepsilon_{F} \circ g F \text {, then } g=f^{\ell} \tag{3.7}
\end{equation*}
$$

assume that $g$ satisfies the hypothesis. Then

$$
\begin{aligned}
f^{\ell}=\left(\varepsilon_{G} \circ G^{\ell} f\right) F^{\ell} \circ G^{\ell} \eta_{F} & =\left(\varepsilon_{F} \circ g F\right) F^{\ell} \circ G^{\ell} \eta_{F} \\
& =\varepsilon_{F} F^{\ell} \circ g F F^{\ell} \circ G^{\ell} \eta_{F} \\
& =\varepsilon_{F} F^{\ell} \circ F^{\ell} \eta_{F} \circ g, \text { by }(2.1) \\
& =g .
\end{aligned}
$$

Similarly, we may define $f^{r}: G^{r} \longrightarrow F^{r}$ by

$$
\begin{equation*}
f^{r}=F^{r} \varepsilon_{G^{r}} \circ F^{r} f G^{r} \circ \eta_{F^{r}} G^{r} \tag{3.8}
\end{equation*}
$$

and, on the way to showing uniqueness, check that it satisfies

$$
\begin{equation*}
f^{r} G \circ \eta_{G^{r}}=F^{r} f \circ \eta_{F^{r}} \tag{3.9}
\end{equation*}
$$

It follows that

$$
\begin{equation*}
f^{r \ell}=f=f^{\ell r} \tag{3.10}
\end{equation*}
$$

and

$$
\begin{equation*}
f F^{\ell} \circ \eta_{F}=G f^{\ell} \circ \eta_{G}=\eta_{f} \tag{3.11}
\end{equation*}
$$

where the generalized expansion $\eta_{f}$, is introduced as an abbreviation.

$$
\begin{equation*}
(g \circ f)^{\ell}=f^{\ell} \circ g^{\ell},(g \circ f)^{r}=f^{r} \circ g^{r} \tag{3.12}
\end{equation*}
$$

For example to prove $f=f^{r \ell}: F^{r \ell} \longrightarrow G^{r \ell}$, it suffices to show that $\varepsilon_{F^{r}} \circ F^{r \ell} f^{r}=\varepsilon_{G^{r}} \circ f G^{r}$, using (3.7) with $f^{r}: G^{r} \longrightarrow F^{r}$ instead of $f$. This can be verified thus

$$
\begin{aligned}
\varepsilon_{F^{r}} \circ F^{r \ell} f^{r} & =\varepsilon_{F^{r}} \circ F\left(F^{r} \varepsilon_{G^{r}} \circ F^{r} f G^{r} \circ \eta_{F^{r}} G^{r}\right) \\
& =\left(\varepsilon_{F^{r}} \circ F F^{r} \varepsilon_{G^{r}}\right) \circ\left(F F^{r} f \circ F \eta_{F^{r}}\right) G^{r}, \text { by }(2.3) \\
& =\left(\varepsilon_{G^{r}} \circ \varepsilon_{F^{r}} G G^{r}\right) \circ\left(F F^{r} f \circ F \eta_{F^{r}}\right) G^{r}, \text { by }(2.1) \\
& =\varepsilon_{G^{r}} \circ\left(\varepsilon_{F^{r}} G \circ F F^{r} f \circ F \eta_{F^{r}}\right) G^{r}, \text { by }(2.3) \\
& =\varepsilon_{G^{r}} \circ\left(f \circ \varepsilon_{F^{r}} F \circ F \eta_{F^{r}}\right) G^{r}, \text { by }(2.1) \\
& =\varepsilon_{G^{r}} \circ f G^{r}, \text { by }(3.1) .
\end{aligned}
$$

To see (3.11), use (3.9) with $f^{\ell}: G^{\ell} \longrightarrow F^{\ell}$ instead of $f: F \longrightarrow G$. Finally, we derive (3.12) by a similar argument.
Equalities (3.1) generalize to

$$
\begin{equation*}
H \varepsilon_{f} \circ \eta_{g} F=g \circ f \text { and } \varepsilon_{g} F^{\ell} \circ H^{\ell} \eta_{f}=(g \circ f)^{\ell} \tag{3.13}
\end{equation*}
$$

For example,

$$
\begin{aligned}
H \varepsilon_{f} \circ \eta_{g} F & =H\left(\varepsilon_{G} \circ G^{\ell}\right) \circ\left(g G^{\ell} \circ \eta_{G}\right) F \\
& =H \varepsilon_{G} \circ H G^{\ell} f \circ g G^{\ell} F \circ \eta_{G} F \\
& =H \varepsilon_{G} \circ g G^{\ell} G \circ G G^{\ell} f \circ \eta_{G} F \\
& =g \circ \varepsilon_{G} G \circ G \eta_{G} \circ f \\
& =g \circ f .
\end{aligned}
$$

Note that $\varepsilon_{F}=\varepsilon_{1_{F}}$, thus (3.1) is a particular case of (3.13).

## 4 Transitions

A 2-category is said to be compact, if every 1-cell has both a left and a right adjoint. A 2-category with only one 0 -cell is also called a strict monoidal category. For a given category $\mathcal{C}$, we will introduce a category $\mathrm{T}(\mathcal{C})$ in which the 2-cells are labeled graphs, called transitions, and show that it is the compact strict monoidal category freely generated by $\mathcal{C}$. As $\mathcal{C}$ is to be embedded in the free category, the objects $A, B, \ldots$ of $\mathcal{C}$ are identified with 1-cells, and the arrows of $\mathcal{C}$ with 2 -cells such that composition in $\mathcal{C}$ becomes vertical composition in $\mathrm{T}(\mathcal{C})$. As there is only one 0 -cell, horizontal composition is defined for arbitrary 1-cells and, in view of (2.1), horizontal composition is also defined for arbitrary 2-cells. Hence, let

$$
\cdots, \mathbf{A}^{(-2)}, \mathbf{A}^{(-1)}, \mathbf{A}^{(0)}, \mathbf{A}^{(1)}, \mathbf{A}^{(2)} \cdots
$$

stand for

$$
\cdots, \mathbf{A}^{\ell \ell}, \mathbf{A}^{\ell}, \mathbf{A} \mathbf{A}^{r}, \mathbf{A}^{r r} \cdots
$$

The 1-cells of $\mathrm{T}(\mathcal{C})$ are strings

$$
\Gamma=\mathbf{A}_{1}^{\left(z_{1}\right)} \cdots \mathbf{A}_{n}^{\left(z_{n}\right)}, z_{i} \in, \quad \mathbf{A}_{i} \in|\mathcal{C}|
$$

where the empty string represents the unit 1. Following pregroup terminology, 1-cells of the form $\mathbf{A}^{(z)}$ are called simple types and strings of simple types are called types. Using letters $A, B$ for simple types, we refer to the integer $z$ such that $A=\mathbf{A}^{(z)}$ as the iterator of $A$ and to $\mathbf{A}$ as the base of $A$. We define

$$
\begin{aligned}
\left(\mathbf{A}_{1}^{\left(z_{1}\right)} \ldots \mathbf{A}_{n}^{\left(z_{n}\right)}\right)^{\ell} & =\mathbf{A}_{n}^{\left(z_{n}-1\right)} \ldots \mathbf{A}_{1}^{\left(z_{1}-1\right)} \\
\left(\mathbf{A}_{1}^{\left(z_{1}\right)} \ldots \mathbf{A}_{n}^{\left(z_{n}\right)}\right)^{r} & =\mathbf{A}_{n}^{\left(z_{n}+1\right)} \ldots \mathbf{A}_{1}^{\left(z_{1}+1\right)}
\end{aligned}
$$

In particular

$$
\left(\mathbf{A}^{(z)}\right)^{\ell}=\mathbf{A}^{(z-1)},\left(\mathbf{A}^{(z)}\right)^{r}=\mathbf{A}^{(z+1)}
$$

It is customary in pregroup grammars to represent contractions of simple types as under-links:

$$
\varepsilon_{A}: A^{\ell} A \longrightarrow 1 \quad A^{\ell} A
$$

By analogy, following the practice of linear logicians, we introduce over-links for expansions of simple types:

$$
\eta_{A}: 1 \longrightarrow A A^{\ell} \quad \stackrel{\rightharpoonup A A^{\ell}}{ }
$$

Representing an arrow $\mathbf{s}: \mathbf{A} \longrightarrow \mathbf{B}$ of $\mathcal{C}$ as a vertical link

we generalize this to vertical links

$$
\begin{array}{cc}
\mathbf{A}^{(2 z)} & \mathbf{B}^{(2 z+1)} \\
\mathbf{s}^{(2 z)} \mid & \mathbf{s}^{(2 z+1)} \mid \\
\mathbf{B}^{(2 z)} & \mathbf{A}^{(2 z+1)}
\end{array}
$$

Again, $\ldots, \mathbf{s}^{(-2)}, \mathbf{s}^{(-1)}, \mathbf{s}^{(0)}, \mathbf{s}^{(1)}, \mathbf{s}^{(2)}, \ldots$ stands for $\ldots, \mathbf{s}^{\ell \ell}, \mathbf{s}^{\ell}, \mathbf{s} \mathbf{s}^{r}, \mathbf{s}^{r r}, \ldots$ It is convenient to declare $\mathbf{s}^{(z)}: \mathbf{A}^{(z)} \longrightarrow \mathbf{B}^{(z)}$ if either $\mathbf{s}: \mathbf{A} \longrightarrow \mathbf{B}$ and $z$ is even or $\mathbf{s}: \mathbf{B} \longrightarrow \mathbf{A}$ and $z$ is odd. We use $s: A \longrightarrow B$ for $\mathbf{s}^{(z)}: \mathbf{A}^{(z)} \longrightarrow \mathbf{B}^{(z)}$ and call arrows of this form simple arrows. Again, we call the
integer $z$ in $s=\mathbf{s}^{(z)}$ the iterator of $s$ and the arrow $\mathbf{s}$ of $\mathcal{C}$ the base of $s$. If $s=\mathbf{s}^{(z)}: A \longrightarrow B, t=$ $\mathbf{t}^{(z)}: B \longrightarrow C$ we define

$$
\begin{aligned}
t \circ s & =(\mathbf{t} \circ \mathbf{s})^{(z)}, \text { if } z \text { is even } \\
& =(\mathbf{s} \circ \mathbf{t})^{(z)}, \text { if } z \text { is odd. }
\end{aligned}
$$

Other convenient meta-notations concerning simple arrows are

$$
\begin{aligned}
s^{\ell} & =\left(\mathbf{s}^{(z)}\right)^{\ell}=\mathbf{s}^{(z-1)}, \\
s^{r} & =\left(\mathbf{s}^{(z)}\right)^{r}=\mathbf{s}^{(z+1)}, \\
1_{\mathbf{A}^{(z)}} & =\left(1_{\mathbf{A}}\right)^{(z)} .
\end{aligned}
$$

It follows from these definitions that $(t \circ s)^{\ell}=s^{\ell} \circ t^{\ell}$ and $(t \circ s)^{r}=s^{r} \circ t^{r}$.
he idea is to extend this graphical representation of contractions, expansions and simple arrows to all 2-cells of the free category, using links labeled by simple arrows.

Horizontal composition can be represented by the juxtaposition of sets of links. For example,

and


Vertical composition can be represented by connecting vertically graphs and identifying a composite path with the corresponding link through its endpoints. For example, $A \varepsilon_{A} \circ \eta_{A} A=A$ we must identify


For $s: B \longrightarrow A$, we represent

$$
\varepsilon_{s}=\varepsilon_{A} \circ A^{\ell} s=\varepsilon_{B} \circ s^{\ell} A: A^{\ell} B \longrightarrow 1 \text { by } \underbrace{A^{\ell} B}_{s}
$$

and then must define vertical composition such that


Similarly,

$$
\eta_{s}=s B^{\ell} \circ \eta_{B}=A s^{\ell} \circ \eta_{A}: 1 \longrightarrow A B^{\ell} \text { is represented by } \begin{gathered}
s \\
A B^{\ell}
\end{gathered} .
$$

In the case where the label is $\mathbf{1}_{A}: A \longrightarrow A$, we omit it in the graphical representation.
Prompted by the motivation above, we introduce the formal notion of a transition between strings of simple types as a special kind of graph. For the category theorist, a graph consists of two sets, the set of nodes N and the set of arrows A , and two functions, called domain and codomain, from A
to N. Graph theorists usually consider a special case of this, the so-called directed graph, where for each pair of nodes $(m, n)$ there is at most one arrow of domain $m$ and codomain $n$, i.e. the set of arrows identifies with a binary relation on the set of nodes. Besides directed graphs, they consider non-directed graphs that is to say symmetric relations, where $(m, n)$ and $(n, m)$ are identified as the edge between $m$ and $n$, denoted $\{m, n\}$. It is the latter version we use in the following. In fact, we will consider labeled non-directed graphs where a map assigns to each node and each edge a label.

Definition 1: Given strings of simple types $\Gamma=C_{1} \cdots C_{m}, \Delta=D_{1} \cdots D_{n}$ a transition $f: \Gamma \longrightarrow \Delta$ is a labeled finite non-directed graph. The nodes of $f$ have the form $(0, i)$ or $(1, k)$ where $C_{i}$ is the label of $(0, i)$ and $D_{k}$ the label of $(1, k), 1 \leq i \leq m, 1 \leq k \leq n$. We will refer to $(0, i)$ as the "position $i$ in the domain" of the transition and to $(1, k)$ as the "position $k$ in the codomain". If $i$ and $k$ are positions either both in the domain or both in the codomain, $i<k$ refers to the order of natural numbers. The edges, called links here, are divided into vertical and horizontal links, the latter being divided into over-links and under-links. The words "vertical", "horizontal" etc. anticipate the graphical representation. The following must hold:

1. A vertical link consists of a position $i$ in the domain and a position $k$ in the codomain. Its label is a simple arrow $s: C_{i} \longrightarrow D_{k}$.
2. An under-link consists of two positions $i$ and $k$ in the domain. If $i<k$, its label is a simple arrow $s: C_{k} \longrightarrow C_{i}^{r}$.
3. An over-link consists of two positions $i$ and $k$ in the codomain. If $i<k$, its label is a simple arrow $s: D_{k}^{r} \longrightarrow D_{i}$.
Moreover,
4. each node is endpoint of exactly one link and every link has two distinct endpoints,
5. if $\{(0, i),(1, k)\}$ and $\{(0, j),(1, l)\}$ are vertical links and $i<j$ in the domain, then $k<l$ in the codomain.
6. if $\{(0, i),(0, k)\}$ is an under-link and $j$ is a position in the domain such that $i<j<k$, then $j$ belongs to an under-link $\{(0, j),(0, l)\}$ such that $i<l<k$. The same holds with "under-link" replaced by "over-link" and "domain" by "codomain".

We will represent the transition $f: \Gamma \longrightarrow \Delta$ geometrically by a planar graph, the domain $\Gamma=C_{1} \ldots C_{m}$ on the top, the codomain $\Delta=D_{1} \ldots D_{n}$ at the bottom, letting the simple types stand for their occurrences, drawing the three kinds of links as their names indicate:


Conditions 5) and 6) then ensure that links do not cross. If the label of a link is an identity $1_{A}$ we may replace it by $A$ or omit it altogether in the graphical representation.

Examples of transitions are the empty graph, denoted 1:1 $\longrightarrow 1$, of empty domain and of empty codomain
or for $s: A \longrightarrow B$
$\frac{B^{\ell} A}{s}$ of domain $A^{\ell} B$ and of empty codomain, ultimately to be denoted

$$
\varepsilon_{s}: B^{\ell} A \longrightarrow 1
$$

or for $t: C \longrightarrow D$
$\stackrel{t}{D C^{\ell}}$, of empty domain and of codomain $D C^{\ell}$, ultimately to be denoted

$$
\eta_{t}: 1 \longrightarrow D C^{\ell} .
$$

This denotation anticipates the fact that $\frac{A^{\ell} B}{s}$ will represent a generalized contraction and $\stackrel{t}{D C^{\ell}}$ a generalized expansion in the compact 2-category of transitions, as shown below. Similarly, a single vertical link

is a transition of domain $A$ and of codomain $B$.
To simplify notation, we use $s: A \longrightarrow B$ both to indicate the simple arrow and the simple transition with domain $A$ and codomain $B$, consisting of a unique vertical link labeled $s$. A somewhat more involved example is

where $s: C \longrightarrow B, r: B \longrightarrow A, t: A \longrightarrow D$ and the missing labels are identities. Note that according to our notation, $s: C \longrightarrow B$ implies $s^{\ell}: B^{\ell} \longrightarrow C^{\ell}=C^{\ell \ell r}$ and therefore $s^{\ell}$ is a correct label for a link under positions 5 and 6 in the domain above.

There is an alternative description of the labels in a transition:
By definition, the label $s=\mathbf{s}^{(z)}$ of a vertical link between position $i$ in the domain and position $k$ in the codomain, is a simple arrow $s: C_{i} \longrightarrow D_{k}$ and therefore the iterator of both $C_{i}$ and $D_{k}$ is $z$. This says that the basic arrow s points downward, i.e. from the domain to the codomain, if $z$ is even, and upward if $z$ is odd. The label $s=\mathbf{s}^{(z)}$ of an under-link "points" from right to left, i.e. $s: C_{k} \longrightarrow C_{i}^{r}$ if $i<k$ in the domain. Hence $z$ is also the iterator of $C_{k}$ and $z-1$ the iterator of $C_{i}$, i.e. $C_{i}=\mathbf{B}^{(z-1)}$ and $C_{k}=\mathbf{A}^{(z)}$ and either s: $\mathbf{A} \longrightarrow \mathbf{B}$ if $z$ is even, or $\mathbf{s}: \mathbf{B} \longrightarrow \mathbf{A}$ if $z$ is odd. This means that in under-links, the base arrow s is directed from the position with the even iterator to the position with the odd iterator.

Similarly, the label $s$ of an over-link between positions $k$ and $i$ in the codomain "points" again from right to left, i.e. $s: D_{k}^{r} \longrightarrow D_{i}$ for $i<k$. This time the iterator $z$ of $s$ coincides with that of $D_{i}$ whereas the iterator of $D_{k}$ is $z-1$, i.e. $D_{i}=\mathbf{B}^{(z)}$ and $D_{k}=\mathbf{A}^{(z-1)}$ and either s: $\mathbf{A} \longrightarrow \mathbf{B}$ if $z$ is even, or $\mathbf{s}: \mathbf{B} \longrightarrow \mathbf{A}$ if $z$ is odd. Hence in over-links, the base arrow $\mathbf{s}$ is directed from the base with the odd iterator to the base with the even iterator.

Consider for example the transitions and their base graphs

where

$$
\begin{array}{cc}
r: \mathbf{E}^{\ell \ell} \longrightarrow \mathbf{A}^{\ell \ell}, & r=\mathbf{r}^{\ell \ell}, \\
q: \mathbf{A}^{\ell} \longrightarrow \mathbf{D}^{\ell}, & q=\mathbf{E} \longrightarrow \mathbf{A} \\
s: \mathbf{q}^{\ell} \longrightarrow & \mathbf{q}: \mathbf{D} \longrightarrow \mathbf{A} \\
u: \mathbf{B}^{\ell}, & s=\mathbf{s}^{\ell}, \\
\mathbf{s}: \mathbf{B} \longrightarrow \mathbf{C}^{\ell}, & u=\mathbf{u}^{\ell}, \\
t: \mathbf{D}^{\ell} \longrightarrow \mathbf{C}^{\ell}, & t=\mathbf{t}^{\ell}, \\
\mathbf{t}: \mathbf{C} \longrightarrow \mathbf{B} \\
\hline \mathbf{D}
\end{array}
$$

In the right hand graph we replaced the links by the basic arrows, the even iterators by + and the odd iterators by - .

We define horizontal composition of transitions as juxtaposition. For example, if $s: C \longrightarrow B$ and $t: A \longrightarrow D$

$$
\frac{B^{\ell} B \frac{D^{\ell} A}{t}}{\varepsilon_{t} \varepsilon_{B}=} \frac{D^{\ell} A}{t} B^{B^{\ell} B} \quad \varepsilon_{B} \eta_{s}=\frac{B^{\ell} B}{\underbrace{s}_{B C^{\ell}}}
$$

or

$$
\eta_{s} t \varepsilon_{B}=\int_{\substack{B^{\ell} B \\ \\ B C^{\ell} D}}^{\left.\overbrace{s}^{A \eta_{s} \varepsilon_{B}=} \quad t\right|_{s} ^{A B^{\ell} B}} .
$$

The examples above are constructed from one-link transitions by horizontal composition, but not all transitions can be obtained thus. Counter-examples are

$$
\begin{gathered}
s \\
\hline t
\end{gathered}
$$

$$
B^{\ell} B^{\ell} B \frac{D^{\ell} A}{t} C
$$

$$
B \overparen{D A^{\ell}} C^{\ell}
$$

$$
\downarrow
$$

In fact, they are obtained by what we call nesting. We can perform it on transitions consisting either of under-links only or of over-links only:

Let $s: A \longrightarrow B$ be a simple arrow.
$\varepsilon_{s}(g): B^{\ell} \Gamma A \longrightarrow 1$ is obtained from $g: \Gamma \longrightarrow 1$ by adding a new under-link from $B^{\ell}$ to $A$ labeled $s$ and
$\eta_{s}(h): 1 \longrightarrow B \Delta A^{\ell}$ is obtained from $h: 1 \longrightarrow \Delta$ by adding a new over-link from $B$ to $A^{\ell}$ labeled $s$.

With this definition, the examples above can be written as

$$
\eta_{s}(\mathbf{1})=\stackrel{s}{B C^{\ell}}=\eta_{s} \quad \varepsilon_{t}(\mathbf{1})=\frac{D^{\ell} A}{t}=\varepsilon_{t}
$$

and

$$
\varepsilon_{s}\left(\varepsilon_{B} \varepsilon_{t}\right)=\underbrace{B^{\ell} \underline{B}^{\ell} B \underbrace{D^{\ell} A} A} \quad \eta_{s}\left(\eta_{t}(\mathbf{1})\right)=B \stackrel{s}{\sqrt{D A^{\ell}}} A^{\ell},
$$

for $s: C \longrightarrow B, \quad t: A \longrightarrow D$.
There is an obvious candidate for vertical composition, as we have seen by the examples at the beginning of the section, namely vertical connection of transitions where every maximal path ${ }^{1}$ is

[^0]replaced by the link through its endpoints. These paths can get quite involved as illustrated by the following example. Connect
to


The connected graph

has a unique maximal path with both endpoints labeled $A$, one in the domain and the other one in the codomain

$$
g \circ f=\left.\right|_{A} ^{A}
$$

Note that the labels of successive links in a connected graph cannot be composed in general: Starting from the right hand upper corner, the labels of the first successive links are : $1_{A}$ for the vertical link of $f, 1_{A}$ for the longest under-link of $g, 1_{A^{\ell}}=\left(1_{A}\right)^{\ell}$, over-link of $f$ starting in the second position of the string, $1_{A^{\ell \ell}}=\left(1_{A}\right)^{\ell \ell}$ etc. However, the base arrows of these links can be composed. Here and below, when we say the "iterator of a position" or "the base of a position", we mean the iterator or the base of the simple type which is the label of the position, and similarly for links.

We form the connection $g ; f$ of $f: \Gamma \longrightarrow \Delta$ with $g: \Delta \longrightarrow \Lambda$ at $\Delta$ as the union of $g$ with $f$ after having renamed the nodes in the codomain of $g$ from $(1, k)$ to $(2, k)$ and those in the domain of $g$ from $(0, i)$ to $(1, i)$. Note that a maximal path in $g ; f$ has its endpoints necessarily in the domain of $f$ or the codomain of $g$. We orient a maximal path as follows: A vertical path, i.e. with one endpoint in the domain of $f$ and the other one in the codomain of $g$, is directed from the top (the domain of $f$ ) to the bottom (the codomain of $g$ ) if the iterator of the endpoint in the domain of $f$ is even, otherwise it is directed from the bottom to the top. If both end-points are in the domain of $f$ the path starts at the endpoint with the even iterator. If both end-points are in the codomain of $g$, it starts at the endpoint with the odd iterator. We assign a label to each path in $g ; f$ as the simple arrow whose base is obtained by composing the base arrows of the successive links beginning at the starting point of the path. The iterator of the label of a vertical path is that of the starting position. If a path has both endpoints in the domain of $f$ the iterator of its label is that of its rightmost endpoint. If it has both endpoints in the codomain of $g$ the iterator of its label is that of its leftmost endpoint.

To define the vertical composition $g \circ f: \Gamma \longrightarrow \Lambda$ of $f: \Gamma \longrightarrow \Delta$ and $g: \Delta \longrightarrow \Lambda$ we connect $f$ with $g$ at $\Delta$ to obtain $g ; f$. The links of $g \circ f$ are obtained by replacing each maximal path of $g ; f$
by a single link through its endpoints. The label of the link consists of the base and the iterator of the replaced path.

To motivate the definition of the label, recall our alternative description of the labels of links. It then becomes obvious that the basic arrows along a path can be composed as indicated. For example, the connected graph

where

| $s: \mathbf{D}^{\ell} \longrightarrow \mathbf{A}^{\ell}$, | $s=\mathbf{s}^{\ell}$, | $\mathbf{s}: \mathbf{A} \longrightarrow \mathbf{D}$ |
| :--- | :--- | :--- |
| $t: \mathbf{C}^{\ell \ell} \longrightarrow \mathbf{B}^{\ell \ell}$, | $t=\mathbf{t}^{\ell \ell}$, | $\mathbf{t}: \mathbf{C} \longrightarrow \mathbf{B}$ |
| $q: \mathbf{D}^{\ell \ell} \longrightarrow \mathbf{C}^{\ell \ell}$, | $q=\mathbf{q}^{\ell \ell}$, | $\mathbf{q}: \mathbf{D} \longrightarrow \mathbf{C}$ |

In this case the label is $\left(1_{\mathbf{B}} \circ \mathbf{q} \circ \mathbf{t} \circ \mathbf{s} \circ 1_{\mathbf{A}}\right)^{\ell}$ which is indeed a simple arrow $(\mathbf{q} \circ \mathbf{t} \circ \mathbf{s})^{\ell}: \mathbf{B}^{\ell} \longrightarrow \mathbf{A}^{\ell}$, corresponding to the transition

$$
\frac{(\mathbf{q} \circ \mathrm{tos})^{\ell}}{\mathbf{A}^{\ell} \mathbf{B}^{l \ell}}
$$

In the next lemma we show that in general the composite of the base arrows with the chosen iterator is an appropriate label for the link replacing the path.

Lemma: (Combing)
Let $f: \Gamma \longrightarrow \Delta$ and $g: \Delta \longrightarrow \Lambda$ be transitions, $\Gamma=A_{1} \cdots A_{n}, \Delta=B_{1} \cdots B_{m}, \Lambda=C_{1} \cdots C_{p}$. Then $g \circ f$ is a transition of domain $\Gamma$ and codomain $\Lambda$.

Proof: Use induction on the length $m$ of the intermediary string $\Delta$. If $m=0$, then $\Delta$ is empty, $f$ has only under-links, $g$ only over-links. Hence all paths in $g ; f$ have length 1 and $g \circ f=g ; f=g f$. For the induction step, assume that $\Delta$ is non-empty and that the property holds for all transitions $f^{\prime}: \Gamma \longrightarrow \Delta^{\prime}$ and $g^{\prime}: \Delta^{\prime} \longrightarrow \Lambda$ connected at an intermediary $\Delta^{\prime}$ shorter than $\Delta$. Note that every path of length at least 2 goes through a position in $\Delta$. In the following argument, we choose a section of a path through such a position consisting of two or three consecutive links. This section will be called a strand and be replaced by a single link, with the same endpoints. There are eight different strands to be considered:

Case 1: Suppose there is a position $j$ in $\Delta$ such that both $f$ and $g$ have a vertical link through $j$. Let $s: A_{i} \longrightarrow B_{j}$ and $t: B_{j} \longrightarrow C_{k}$ be the corresponding labels. Then $f=f_{1} s f_{2}$ and $g=g_{1} t g_{2}$ where $f_{i}: \Gamma_{i} \longrightarrow \Delta_{i}, g_{i}: \Delta_{i} \longrightarrow \Lambda_{i}$ for $i=1,2$. By induction hypothesis, $g_{i} \circ f_{i}: \Gamma_{i} \longrightarrow \Lambda_{i}$ is a transition, for $i=1,2$ and therefore

$$
g \circ f=\left(g_{1} \circ f_{1}\right)(t \circ s)\left(g_{2} \circ f_{2}\right)
$$

(Strand 1)


Case 2: (Strand 2.1) to (Strand 2.6)
If $\Delta$ does not have such a position, assume first that $g$ has at least one under-link. Then there is a position $j$ in $\Delta$ such that $j$ and $j+1$ form an under-link of $g$. Let $\Delta^{\prime}$ be obtained from $\Delta$ by omitting $B_{j} B_{j+1}$ and $g^{\prime}$ from $g$ by omitting the under-link through $j$ and $j+1$. Clearly, $g^{\prime}$ is a transition from $\Delta^{\prime}$ to $\Lambda$. Next, consider the links determined by the positions $j$ and $j+1$ in the codomain of $f$, say $i\{(\gamma, i),(1, j)\}$ and $\{(1, j+1),(\delta, k)\}$, where $\gamma, \delta \in\{0,1\}$. Note that two consecutive positions $j, j+1$ in $\Delta$ cannot simultaneously form an over-link of $f$ and an under-link of $g$. Indeed, the former would imply that the iterator of $B_{j}$ is greater than the iterator of $B_{j+1}$, whereas the latter would imply the contrary. Hence, $i$ and $k$ are both different from $j$ and from $j+1$. We obtain $f^{\prime}$ from $f$ by omitting the two links $\{(\gamma, i),(1, j)\}$ and $\{(1, j+1),(\delta, k)\}$ and adding the new link $\{(\gamma, i),(\delta, k)\}$. For each strand, we verify that the labels (or their adjoints) of the three consecutive links can be composed, providing thus the label for $\{(\gamma, i),(\delta, k)\}$. Then the maximal paths of $g ; f$ identify with the maximal paths of $g^{\prime} ; f^{\prime}$. Hence by definition, $g \circ f=g^{\prime} \circ f^{\prime}$. The property follows then by induction hypothesis.

The under-link from $B_{j}$ to $B_{j+1}$ being fixed in the next 6 cases, let $t: B_{j+1} \longrightarrow B_{j}^{r}$ be its label.
Case 2.1: Both positions $i$ and $k$ are in the domain of $f$.
As links do not cross, we have $i<k$. Let $q: A_{i} \longrightarrow B_{j}$ and $s: A_{k} \longrightarrow B_{j+1}$ be the labels of the corresponding vertical links. According to the notations introduced earlier, $q^{r}: B_{j}^{r} \longrightarrow A_{i}^{r}$ and therefore $q^{r} \circ t \circ s$ is defined and is a simple arrow $q^{r} \circ t \circ s: A_{k} \longrightarrow A_{i}^{r}$.
(Strand 2.1)


Note that the positions between $i$ and $k$ in the domain must be linked by under-links of $f$, defining thus a subtransition $f_{3}$ of codomain 1 of $f$. Therefore $f=f_{1} t^{\ell} f_{3} s f_{2}$. Replacing the two vertical links $\{(0, i),(1, j)\}$ and $\{(0, k),(1, j+1)\}$ by a single under-link $\{(0, i),(0, k)\}$ and leaving the other links of $f$ unchanged we obtain a transition $f^{\prime}$ from $\Gamma$ to $\Delta^{\prime}$.

Case 2.2: Position $i$ is in the domain, position $k$ in the codomain of $f$.
As links do not cross, $j+1<k$. The label of the vertical link is a simple arrow $q: A_{i} \longrightarrow B_{j}$ and the label of the over-link is a simple arrow $s: B_{k}^{r} \longrightarrow B_{j+1}$. Then $s^{\ell}: B_{j+1}{ }^{\ell} \longrightarrow B_{k}$ and $t^{\ell}: B_{j} \longrightarrow B_{j+1}^{\ell}$ and therefore $s^{\ell} \circ t^{\ell} \circ q: A_{i} \longrightarrow B_{k}$. Hence
(Strand 2.2)


Case 2.3: Position $i$ is in the codomain, position $k$ in the domain of $f$.
As links do not cross, $i<j$. Then $q: B_{j}^{r} \longrightarrow B_{i}, s: A_{k} \longrightarrow B_{j+1}$ and $q \circ t \circ s: A_{k} \longrightarrow B_{i}$.
(Strand 2.3)

Case 2.4: Both positions $i$ and $k$ are in the codomain of $f$.
Case 2.4.1: $i<j$ and $j+1<k$
Let $q$ be the label of the over-link between $i$ and $j, s$ the label of the over-link between $j+1$ and $k$. Then $q: B_{j}^{r} \longrightarrow B_{i}, s: B_{k}^{r} \longrightarrow B_{j+1}$ and therefore $q \circ t \circ s: B_{k}{ }^{r} \longrightarrow B_{i}$.
(Strand 2.4.1)

$$
\stackrel{q}{\stackrel{s}{B_{i} \ldots B_{j} B_{j+1} \ldots B_{k}}} \stackrel{s}{t} \quad \text { replaced by } \quad \stackrel{q \circ \text { tos }}{B_{i} \ldots \ldots B_{k}}
$$

Note that the positions between $i$ and $j$ are linked by over-links in $f$ and ditto for the positions between $j+1$ and $k$. Hence $f^{\prime}$ is again a transition from $\Gamma$ to $\Delta^{\prime}$.

Case 2.4.2: $j<i$ and $j+1<k$.
As links do not cross, it follows that $k<i$. The label of the over-link between $i$ and $j$ is a simple arrow $q: B_{i}^{r} \longrightarrow B_{j}$. The label of the over-link between $j+1$ and $k$ is a simple arrow $s: B_{k}^{r} \longrightarrow B_{j+1}$, therefore $s^{\ell}: B_{j+1}^{\ell} \longrightarrow B_{k}$. Hence $s^{\ell} \circ t^{\ell} \circ q: B_{i}^{r} \longrightarrow B_{k}$.
(Strand 2.4.2)

Case 2.4.3: $i<j$ and $k<j+1$.
As labels we have $q: B_{j}^{r} \longrightarrow B_{i}$ and $s: B_{j+1}^{r} \longrightarrow B_{k}$. Hence $s \circ t^{r} \circ q^{r}: B_{i}{ }^{r} \longrightarrow B_{k}$
(Strand 2.4.3)

$$
\begin{array}{|c}
\overbrace{}^{q} \\
B_{k} \ldots B_{i} \ldots B_{B_{j}}^{B_{j+1}}
\end{array} \quad \text { replaced by } \begin{aligned}
& B_{k} \ldots t^{r} \circ q^{r} \\
& B_{k} \ldots B_{i} \ldots
\end{aligned}
$$

Case 3: There remains the case where $g$ has no under-links. As we are in the case where no position in $\Delta$ belongs both to a vertical link in $g$ and to a vertical link in $f$, the latter must have over-links. Hence there is a position $j$ in the codomain of $f$ linked to $j+1$ in $f$. Let $i$ and $k$ be the positions in the codomain of $g$ such that $i$ is linked to $j$ and $j+1$ to $k$ in $g$. As links do not cross, $i<k$. Then the labels of these links satisfy $s: B_{j+1}^{r} \longrightarrow B_{j}, t: B_{j} \longrightarrow C_{i}, u: B_{j+1} \longrightarrow C_{k}$. Therefore $u^{r}: C_{k}^{r} \longrightarrow B_{j+1}^{r}$ and $t \circ s \circ u^{r}: C_{k}^{r} \longrightarrow C_{i}$.
(Strand 3)


This completes the proof.
Note that the vertical composition of two transitions can be computed in time proportional to the number of links in the transitions. Indeed, it suffices to follow a maximal path exactly once, computing the label on the way as indicated in the definition.

Proposition: $T(\mathcal{C})$ is a compact strict monoidal category.
Proof: Vertical composition is clearly associative, the identity $1_{A_{1} \ldots A_{n}}: A_{1} \ldots A_{n} \longrightarrow A_{1} \ldots A_{n}$ consists of the obvious vertical links through corresponding simple types. The label of the link
connecting position $i$ in the domain to position $i$ in the codomain is the identity of the simple type $A_{i}$. Recall that $\Gamma$ is identified with $1_{\Gamma}$. Then the equality (2.1)

$$
g \Lambda \circ \Delta f=\Theta f \circ g \Gamma=g f, \text { for } f: \Gamma \longrightarrow \Lambda, g: \Delta \longrightarrow \Theta
$$

is straightforward.
Compactness follows, if

$$
A \varepsilon_{A} \circ \eta_{A} A=A \text { and } \varepsilon_{A} A^{\ell} \circ A^{\ell} \eta_{A}=A^{\ell}
$$

holds. By (3.3), it is enough to verify this for all simple types $A$, namely that


The Combing Lemma is the categorical version of cut-elimination in compact bilinear logic, established in [Buszkowski]. Indeed, the categorical equality defines an equivalence relation on proofs such that transitions are cut-free representatives of equivalence classes. Besides providing a graphical representation of cut-free proofs, the categorical result tells us more: not only can we derive from $f: \Gamma \longrightarrow \Delta$ and $g: \Delta \longrightarrow \Lambda$ the existence of a cut-free $h: \Gamma \longrightarrow \Lambda$, but also show that this new $h: \Gamma \longrightarrow \Lambda$ is equivalent to $g ; f$.

## Justifying notation:

We have introduced $s^{\ell}=\left(\mathbf{s}^{(z)}\right)^{\ell}=\mathbf{s}^{(z-1)}, s^{r}=\left(\mathbf{s}^{(z)}\right)^{r}=\mathbf{s}^{(z+1)}$ for simple arrows as a convenient notation in the meta-language. Now we can show that they indeed denote the left respectively right adjoint in the compact 2-category of transitions, for example we show that $s^{\ell}=\varepsilon_{B} A^{\ell} \circ B^{\ell} s A^{\ell} \circ B^{\ell} \eta_{A}$ :

where, from left to right, we made the replacements (Strand 2.1), (Strand 2.2) and (Strand 1).
Similarly, "nesting" can now be described in the language of compact 2-categories. One verifies easily that for transitions $g: \Gamma \longrightarrow 1$ and $h: 1 \longrightarrow \Delta$ and simple $s: A \longrightarrow B$,

$$
\varepsilon_{s}(g)=\varepsilon_{s} \circ B^{\ell} g A: B^{\ell} \Gamma A \longrightarrow 1 \text { and } \eta_{s}(h)=B h A^{\ell} \circ \eta_{s}: 1 \longrightarrow B \Delta A^{\ell}
$$

For example,


Theorem: $T(\mathcal{C})$ is the free compact strict monoidal category generated by $\mathcal{C}$.
Sketch of proof: (For a complete proof see the Appendix below.)
A functor $\Phi: \mathcal{C} \longrightarrow U(\mathcal{M})$ into the underlying category of another compact strict monoidal category $\mathcal{C}$, can be extended to a strict monoidal functor $\bar{\Phi}: T(\mathcal{C}) \longrightarrow \mathcal{M}$ as follows:
First we define $\bar{\Phi}$ in the obvious way on simple types and simple arrows and, writing $\bar{A}$ for $\bar{\Phi}(A)$ and $\bar{s}$ for $\bar{\Phi}(s)$, we define $\bar{\Phi}$ for generalized contractions and expansions as

$$
\begin{aligned}
& \bar{\Phi}\left(\varepsilon_{s}\right)=\overline{\varepsilon_{s}}=\varepsilon_{\bar{s}} \\
& \bar{\Phi}\left(\eta_{s}\right)=\overline{\eta_{s}}=\eta_{\bar{s}} .
\end{aligned}
$$

Then, we extend $\bar{\Phi}$ inductively to all transitions by making it commute with horizontal composition and nesting:

$$
\begin{aligned}
& \overline{f g}=\bar{f} \bar{g} \\
& \frac{\varepsilon_{s}(f)}{\overline{\eta_{s}(g)}}=\varepsilon_{\bar{s}} \circ \bar{B} \bar{B}^{\ell} \bar{f} \bar{A}, s: A \longrightarrow B \text { simple } \\
& \bar{g} \circ \eta_{\bar{s}}, s: A \longrightarrow B \text { simple. }
\end{aligned}
$$

By construction, $\bar{\Phi}$ preserves horizontal composition, $\varepsilon$ and $\eta$. As uniqueness is obvious, it only remains to show that $\bar{\Phi}$ preserves vertical composition. To do this, we follow the Combing Lemma. For the induction step, we prove Case 1 thus

$$
\begin{aligned}
\overline{g \circ f} & =\overline{\left(g_{1} \circ f_{1}\right)(t \circ s)\left(g_{2} \circ f_{2}\right)} \\
& =\left(\overline{g_{1} \circ f_{1}}\right)(\overline{t \circ s})\left(\overline{g_{2} \circ f_{2}}\right) \\
& =\left(\overline{g_{1}} \circ \overline{f_{1}}\right)(\bar{t} \circ \bar{s})\left(\overline{g_{2}} \circ \overline{f_{2}}\right) \\
& =\overline{g_{1}} \overline{\bar{g}} \overline{g_{2}} \circ \overline{f_{1}} \bar{s} \overline{f_{2}} \\
& =\bar{g} \circ \bar{f}
\end{aligned}
$$

In the other cases we use the intermediary transitions $g^{\prime}$ and $f^{\prime}$ for which $g \circ f=g^{\prime} \circ f^{\prime}$ and therefore also $\overline{g \circ f}=\overline{g^{\prime} \circ f^{\prime}}$. As by induction hypothesis $\overline{g^{\prime} \circ f^{\prime}}=\overline{g^{\prime}} \circ \overline{f^{\prime}}$, it remains to show that $\bar{g} \circ \bar{f}=\overline{g^{\prime}} \circ \overline{f^{\prime}}$. This requires some care as we must express the seven definitions of $g^{\prime}$ and $f^{\prime}$ of the Combing Lemma in the language of $T(\mathcal{C})$. Instead of carrying out the details of this program for all seven cases, a different proof will be presented in the Appendix, relating transitions to derivations in the free pregroup.

This theorem provides a decision procedure for the equational theory of strict compact monoidal categories given by the axioms of strict monoidal categories together with 3.1 to 3.4. The procedure applies then also to any definitially equivalent theory such as that of compact non-symmetric starautonomous categories where the unit of the tensor product is a dualizing object, [Barr]. Indeed, to decide whether $f=g$ can be derived, interpret both terms in the category of transitions.

## 5 The free strict compact 2-category generated by a given 2-graph

We can modify the above construction to the compact 2-category freely generated from a given 2 -graph. To simplify matters, we will assume that the 2 -cells of the 2 -graph form a category.


Then the construction is the same as above. However, if $\mathbf{A}: \mathbf{M} \longrightarrow \mathbf{N}$ is a 1 -cell and $z \in \mathbb{Z}$, we have to require that the simple type $\mathbf{A}^{(z)}$ is 1-cell such that

$$
\begin{aligned}
& \mathbf{A}^{(z)}: \mathbf{M} \longrightarrow \mathbf{N}, \text { if } z \text { is even } \\
& \mathbf{A}^{(z)}: \mathbf{N} \longrightarrow \mathbf{M}, \text { if } z \text { is odd. }
\end{aligned}
$$

Types are now paths, i.e. $\mathbf{A}_{1}^{\left(z_{1}\right)} \ldots A_{n}^{\left(z_{n}\right)}$ must satisfy

$$
\mathbf{A}_{i}^{\left(z_{i}\right)}: \mathbf{N}_{i} \longrightarrow \mathbf{N}_{i+1}, 1 \leq i \leq n-1
$$

Then the 1-cells of the free compact 2-category are the types and the 2-cells are the transitions between types.

As a particular case, let $\mathcal{C}$ consist of two 0 -cells, $\mathbf{M}$ and $\mathbf{N}$, a 1-cell $\mathbf{F}: \mathbf{M} \longrightarrow \mathbf{N}$ and the identity of $\mathbf{F}$ as the unique 2-cells. Let $G=\mathbf{F}^{r}$ and only consider transitions with domain and codomain of the form $G \mathbf{F} G \ldots \mathbf{F} G$ where $\mathbf{F} G$ is repeated $n$ times, $n \geq 0$. Then the only possible under-links are between neighboring $\mathbf{F} G$ in the domain and the only possible over-links between neighboring $G \mathbf{F}$ in the codomain. Hence the first position in the domain always belongs to a vertical link. When connecting two such transitions, say


Strands 2.4.2 and 2.4.3 do not occur. More generally, there is no nesting. These graphs are considered in [Dos̆en 02] under the name of friezes. The connection between a free adjoint functor pair and cut-elimination is investigated in [Došen 99]. In compact 2-categories the infinite number of adjoints requires more involved graphs for the computation of composition, like the spiral in Example 1. The 1-cells involving $\mathbf{F}$ and $\mathbf{F}^{r}$ only are so-called "linear" types, see [Degeilh-Preller], where it has been shown that there is at most one transition between two given types. In particular, linear types do not capture differences in meaning for which the presence of both right and left adjoint is required. Linguistic applications call for right and left iterated adjoints, e.g. to describe the Chomskyan trace, see [Lambek 99].

One may wish to generalize the present results to bicategories, using the notions of adjunctions on bicategories (see e.g. [Lambek 04]), but we will refrain from doing so here. The special case of compact symmetric monoidal categories has been treated in a classical paper by [Kelly - Laplaza]. They did not actually construct the free such category, instead they established the important result that equations between morphisms in the language of such categories follow from the axioms if and only if they hold, up to isomorphism, for the graphs. In the situation we have discussed here, the graphs have to be equal.

## 6 Conclusion

We have described the 2 -cells of $T(\mathcal{C})$, the free compact monoidal 2-category generated by $\mathcal{C}$ as labeled transition systems. These transition systems draw their labels from $\mathcal{C}$ and are closed under parallel and sequential composition. In the case where $\mathcal{C}$ is itself freely generated by a labeled graph, the edges of this graph stand for non-logical axioms or "information". Both left and right adjoint provide a mechanism for storing this information. It follows from the above that equality in $T \mathcal{C}$ ) is decidable, if the equality of arrows in $\mathcal{C}$ is. This is in particular the case, if $\mathcal{C}$ is freely generated by a labeled graph. The reductions constructed when analyzing syntax with a pregroup grammar are particular transitions. As different reductions give rise to different semantical interpretations, transitions are an indispensable step from pregroup grammars to discourse representation.

## 7 Appendix (by Anne Preller)

To prove that $T(\mathcal{C})$ is the free compact strict monoidal category, we define the extension $\bar{\Phi}$ : $T(\mathcal{C}) \longrightarrow \mathcal{M}$ of the functor $\Phi$ from $\mathcal{C}$ to a compact strict monoidal category $\mathcal{M}$ as indicated in the outline of the proof in Section 4. First we check that $\bar{\Phi}$ is well defined. The other property left to be shown is that $\bar{\Phi}$ commutes with vertical composition. The proof outlined in Section 4 is based on the idea that the Combing Lemma can be expressed in purely categorical terms. Though the equalities corresponding to the eight cases of the Combing Lemma can be shown to hold in $\mathcal{M}$, the proof below follows a different line: it relates transitions directly to the derivations in free pregroups defined in [Lambek 99].

We remarked in Section 4 that an arbitrary transition can be obtained from single links by the graphical operations of juxtaposition and nesting. To express these operations in categorical language, we distinguish the horizontal normal forms among the expressions of the language of compact strict monoidal categories with constants in $\mathcal{C}$.

## Definition 1 (Horizontal normal form)

Every simple arrow $s: A \longrightarrow B$, every generalized contraction $\varepsilon_{s}: B^{\ell} A \longrightarrow 1$ and every generalized expansion $\eta_{s}: 1 \longrightarrow B A^{\ell}$ is a horizontal normal form.
An arbitrary horizontal normal form is obtained from them by the following rules

$$
\begin{array}{ll}
\text { (Horizontal composition) } & \frac{f: \Gamma \longrightarrow \Delta \text { normal } g: \Theta \longrightarrow \Lambda \text { normal }}{f g: \Gamma \Theta \longrightarrow \Delta \text { normal }} \\
\text { (Nesting Contraction) } & \frac{f: \Gamma \longrightarrow 1 \text { normal } s: A \longrightarrow B \text { simple }}{\varepsilon_{s} \circ B^{\ell} f A: B^{\ell} \Gamma A \longrightarrow 1 \text { normal }} \\
\text { (Nesting Expansion) } & \frac{f: 1 \longrightarrow \Delta \text { normal } s: A \longrightarrow B \text { simple }}{\eta_{s} \circ B f A^{\ell}: 1 \longrightarrow B \Delta A^{\ell} \text { normal }}
\end{array}
$$

where the Horizontal Composition rule does not apply to $u: \Gamma \longrightarrow 1$ and $o: 1 \longrightarrow \Lambda$.
Note that the Horizontal Composition rule applies to $o: 1 \longrightarrow \Lambda$ and $u: \Gamma \longrightarrow 1$. The order $u: \Gamma \longrightarrow 1$ and $o: 1 \longrightarrow \Lambda$ is excluded because $u o=o u$ holds in all 2-categories by (2.7). Thus, only ou is a normal expression. This, together with the fact that $\mathbf{1}$ is not a normal expression, makes it possible to assert the uniqueness of horizontal normal forms:
Lemma 1 (Horizontal normal form)
Every non empty transition $f: A_{1} \ldots A_{m} \longrightarrow B_{1} \ldots B_{n}$ can be expressed in horizontal normal form, which is unique up to associativity of horizontal composition.

Proof: Use induction on the number of links in $f$. At least one of $n$ or $m$ is greater than 0 . First, assume that $m>0$. Distinguish two cases:

1. The last position $m$ of $\Gamma$ is linked to a position $k$ in the codomain $\Delta$ with label $s$.


Then the other links of $f$ can be divided into those with no endpoint to the right of $k$ and those with both endpoints to the right of $k$. The former set of links defines a transition $g: A_{1} \ldots A_{m-1}$ $\longrightarrow B_{1} \ldots B_{k-1}$, and the latter a transition $h: 1 \longrightarrow B_{k+1} \ldots B_{n}$ such that $f=g s h$.
2. The last position $m$ in the domain is linked to a position $k<m$ in the domain.

$$
\begin{gathered}
A_{1} \ldots A_{k-1} \underbrace{A_{k} \ldots A_{m}}_{s} \\
B_{1} \ldots B_{n}
\end{gathered}
$$

Let $g$ consist of the links of $f$ with endpoints in the codomain or to the left of $k$ in the domain, and let $h$ consist of the links with both endpoints in the domain strictly between $k$ and $m$. Then $g: A_{1} \ldots A_{k-1} \longrightarrow B_{1} \ldots B_{n}, h: A_{k+1} \ldots A_{m-1} \longrightarrow 1$ and $f=g \varepsilon_{s}(h)$

Else, suppose $m=0$ and $n>0$. Now consider the link through the last position $n$ in the codomain. Let $t$ be its label. The other endpoint of this link is a position $j<n$ in the codomain:

$$
B_{1} \ldots B_{j-1} \stackrel{t}{B_{j} \ldots B_{n}}
$$

Then the links which have both endpoints to the left of $j$ form a transition $g: 1 \longrightarrow B_{1} \ldots B_{j-1}$ and the links with both endpoints between $j$ and $n$ form a transition $h: 1 \longrightarrow B_{j+1} \ldots B_{n-1}$ such that $f=g \eta_{t}(h)$.

From the existence of a unique normal form for a transition, it follows at once that the canonical extension $\bar{\Phi}$ is well defined. We recall the definition using $\overline{()}$ instead of $\bar{\Phi}$ :
(I) $\overline{\overline{\mathbf{A}^{(0)}}}=\Phi(\mathbf{A}), \mathbf{A}$ object of $C$ $\overline{\mathbf{s}^{(0)}}=\Phi(\mathbf{s}), \mathbf{s}$ arrow of $C$
(II) $\overline{\mathbf{A}^{n+1}}={\overline{\mathbf{A}^{(n)}}}^{r}, \overline{\mathbf{A}^{(-n-1)}}={\overline{\mathbf{A}^{(-n)}}}^{\ell}$, for $0 \leq n$ $\overline{\mathbf{s}^{(n+1)}}={\overline{\mathbf{s}^{(n)}}}^{r}, \overline{\mathbf{s}^{(-n-1)}}={\overline{\mathbf{s}^{(-n)}}}^{\ell}$, for $0 \leq n$
(III) $\overline{\Gamma \Delta}=\bar{\Gamma} \bar{\Delta} \overline{f g}=\bar{f} \bar{g}$
(IV) $\overline{\varepsilon_{s}}=\varepsilon_{\bar{s}}$
$\overline{\eta_{s}}=\eta_{\bar{s}}$ $\overline{\varepsilon_{s}(f)}=\varepsilon_{\bar{s}} \circ \bar{B} \bar{f}^{\ell} \bar{A}=\varepsilon_{\bar{s}}(f), f: \Gamma \longrightarrow \mathbf{1}, s: A \longrightarrow B$ simple $\overline{\eta_{s}(g)}=\bar{B} \bar{g} \bar{A}^{\ell} \circ \eta_{\bar{s}}=\eta_{\bar{s}}(g), g: \mathbf{1} \longrightarrow \Delta, s: A \longrightarrow B$ simple
(V) $\overline{\mathbf{1}}=1, \overline{1_{\Gamma}}=1_{\bar{\Gamma}}$.

By definition, $\bar{\Phi}$ preserves horizontal composition and the identities. If the left and right adjoints of 1 -cells are part of the signature of $\mathcal{M}, \bar{\Phi}$ preserves left and right adjoints only up to isomorphism in general. For example, we may only have $(G H)^{\ell} \cong H^{\ell} G^{\ell}$ in $\mathcal{M}$. However, as only the existence of left and right adjoints of 1-cells is assumed in the definition in Section 3, a functor of 2-categories which preserves left and right adjoint up to isomorphism may still be correctly called a functor of compact 2-categories.

Finally, we must show that $\bar{\Phi}$ commutes with vertical composition. This is easily verified if the composed transitions are simple arrows or if one of them is an identity. In the general case, the idea is to prove the property for transitions that consist essentially of just one link, the so-called single step transitions, and to show that an arbitrary transition is equal to a vertical composition of single steps.

## Definition 3 (Single step)

A single step is a 2-cell of one of the following forms

where $s: A \longrightarrow B$ is a simple arrow.
This definition uses categorical language only, hence replacing $s$ by $\bar{s}$, we may say that the canonical map preserves single steps, i.e. $\overline{\Gamma s \Delta}=\bar{\Gamma} \bar{s} \bar{\Delta}, \overline{\Gamma \varepsilon_{s} \Delta}=\bar{\Gamma} \varepsilon_{\bar{s}} \bar{\Delta}$ and $\overline{\Gamma \eta_{s} \Delta}=\bar{\Gamma} \eta_{\bar{s}} \bar{\Delta}$. Single steps generate all transitions, as follows from Lemma 1 and the following Lemma 2:

Lemma 2 (Vertical decomposition of horizontal normal forms)
Every horizontal normal form $f: A_{1} \ldots A_{n} \longrightarrow B_{1} \ldots B_{\underline{m}}$ can be expressed as a vertical composition of single steps $f=f_{1} \circ \ldots \circ f_{n}$ such that $\bar{f}=\overline{f_{1}} \circ \ldots \circ \overline{f_{n}}$.

The proof of Lemma 2 is straightforward by induction on the derivation of the horizontal normal form of $f$. The distributivity laws (2.3) intervene if one of the nesting rules was applied. If the horizontal composition rule was applied, the argument is as follows:
For $h: \Gamma \longrightarrow \Theta$ and $g: \Delta \longrightarrow \Lambda$, the equalities

$$
g \Theta \circ \Delta h=g h=\Lambda h \circ g \Gamma
$$


hold in a an arbitrary 2-category by (2.1), therefore

$$
\bar{g} \bar{\Theta} \circ \bar{\Delta} \bar{h}=\bar{g} \bar{h}=\bar{\Lambda} \bar{h} \circ \bar{g} \bar{\Gamma}
$$

Hence,

$$
\overline{g \Theta \circ \Delta h}=\overline{g h}=\bar{g} \bar{h}=\bar{g} \bar{\Theta} \circ \bar{\Delta} \bar{h}=\overline{g \Theta} \circ \overline{\Delta h}
$$

and similarly,

$$
\overline{\Lambda h \circ g \Gamma}=\overline{\Lambda h} \circ \overline{g \Gamma}
$$

In particular, if $h$ and $g$ are single steps, then $\Lambda h, g \Gamma, g \Theta$ and $\Delta h$ are again single steps. We call $\Lambda h$ and $g \Gamma$ respectively $g \Theta$ and $\Delta h$ disjoint, because the essential links can not interact. This operation, which switches two disjoint single steps, has given the Switching Lemma of [Lambek 99] its name.

In general, however, Lemma 2 is not sufficient to show that $\overline{g \circ f}=\bar{g} \circ \bar{f}$, because $g \circ f$ is in general not in horizontal normal form. All we can conclude form this is that $g \circ f=g_{1} \ldots \circ g_{n} \circ \circ f_{1} \ldots f_{m}$ and that $\bar{g} \circ \bar{f}=\overline{g_{1}} \ldots \circ \overline{g_{n}} \circ \overline{f_{1}} \ldots \overline{f_{m}}$. Our next task is to associate to a vertical composition of single steps $f_{1} \circ \ldots \circ f_{n}$ a normal form $f$ such that

$$
\begin{aligned}
\frac{f_{1}}{\ldots \circ \frac{f_{n}}{f_{1}} \circ \ldots \circ \overline{f_{n}}}=\frac{f}{f}
\end{aligned}
$$

and therefore

$$
\overline{f_{1} \circ \ldots \circ f_{n}}=\overline{f_{1}} \circ \ldots \circ \overline{f_{n}}
$$

The other operations introduced in the Switching Lemma imply this equality for $n=2$ by replacing two successive single steps by one single step. We recall them as Operations (1) to (4) below and prove that the replaced steps are equal to the replacing step.

## (Switching Operations)

(0) Switch two disjoint steps.

$$
f_{i} \circ f_{i+1}=f_{i+1} \circ f_{i} \quad \text { and } \quad \overline{f_{i} \circ f_{i+1}}=\overline{f_{i}} \circ \overline{f_{i+1}} .
$$

In Operations (1) to (4) below, the two replaced steps are non-disjoint:
(1) Replace two induced steps by a single induced step.


As the equality is an instance of the distributive laws in 2-categories, we also have

$$
\bar{\Gamma} \bar{t} \bar{\Delta} \circ \bar{\Gamma} \bar{s} \bar{\Delta}=\bar{\Gamma}(\bar{t} \circ \bar{s}) \bar{\Delta}=\bar{\Gamma} \overline{t \circ s} \bar{\Delta} .
$$

(2) Replace a generalized expansion followed by a generalized contraction by an induced step.
(2a) The generalized contraction is on the left:

where $t: B \longrightarrow A$ and $s: C \longrightarrow B$. The equalities

$$
\begin{aligned}
\varepsilon_{t} C^{\ell} \circ A^{\ell} \eta_{s} & =\left(\varepsilon_{A} \circ A^{\ell} t\right) C^{\ell} \circ A^{\ell}\left(s C^{\ell} \circ \eta_{C}\right) \\
& =\varepsilon_{A} C^{\ell} \circ A^{\ell} t C^{\ell} \circ A^{\ell} s C^{\ell} \circ A^{\ell} \eta_{C} \\
& =\varepsilon_{A} C^{\ell} \circ A^{\ell}(t \circ s) C^{\ell} \circ A^{\ell} \eta_{C} \\
& =(t \circ s)^{\ell}, \text { by }(3.5)
\end{aligned}
$$

and

$$
\Gamma \varepsilon_{t} C^{\ell} \Delta \circ \Gamma A^{\ell} \eta_{s} \Delta=\Gamma\left(\varepsilon_{t} C^{\ell} \circ A^{\ell} \eta_{s}\right) \Delta=\Gamma(t \circ s)^{\ell} \Delta
$$

hold in arbitrary 2-categories. Recall that the canonical map commutes with vertical composition of simple arrows and the adjoints of simple arrows

$$
\overline{(t \circ s)^{\ell}}=(\bar{t} \circ \bar{s})^{\ell} .
$$

Hence

$$
\begin{aligned}
\overline{\Gamma \varepsilon_{t} C^{\ell} \Delta \circ \Gamma A^{\ell} \eta_{s} \Delta} & =\overline{\Gamma(t \circ s)^{\ell} \Delta} \\
& =\bar{\Gamma} \overline{(t \circ s)^{\ell}} \bar{\Delta} \\
& =\overline{\bar{\Gamma}}(\bar{t} \circ \bar{s})^{\ell} \bar{\Delta} \\
& =\bar{\Gamma} \varepsilon_{\bar{t}} \bar{\Delta} \circ \bar{\Gamma} \eta_{\bar{s}} \bar{\Delta} \\
& =\overline{\Gamma \varepsilon_{t} \Delta} \circ \overline{\Gamma \eta_{s} \Delta} .
\end{aligned}
$$

(2b) The generalised contraction is on the right:


The proof is similar, using an instance of (3.13)

$$
D \varepsilon_{t} \circ \eta_{q} B=q \circ t
$$

(3) Replace an induced step followed by a generalized contraction by a generalized contraction.
(3a) The essential link of the induced step is on the right

where $t: B \longrightarrow A, s: C \longrightarrow B$.
Indeed,

$$
\varepsilon_{t} \circ A^{\ell} s=\varepsilon_{A} \circ A^{\ell} t \circ A^{\ell} s=\varepsilon_{A} \circ A^{\ell}(t \circ s)=\varepsilon_{t \circ s}
$$

and

$$
\Gamma \varepsilon_{t} \Delta \circ \Gamma A^{\ell} s \Delta=\Gamma\left(\varepsilon_{t} \circ A^{\ell} s\right) \Delta=\Gamma \varepsilon_{t \circ s} \Delta
$$

hold in all compact 2-categories, hence

$$
\bar{\Gamma} \bar{\varepsilon}_{\bar{t}} \bar{\Delta} \circ \bar{\Gamma} \overline{A^{\ell}} \bar{s} \bar{\Delta}=\bar{\Gamma} \varepsilon_{\bar{t} \circ \bar{s}} \bar{\Delta}
$$

(3b) The essential link of the induced step is on the left.
(4) Replace a generalized expansion and a following induced step by a generalized expansion.
(4a) The essential link of the induced step is on the right.
(4b) The essential link of the induced step is on the left.
The proofs of Cases (3b), (4a) and (4b) are left to the reader.
There are four cases which are not included in the switching operations, namely the cases where the two consecutive single steps $f_{i} \circ f_{i+1}$ are either both generalized contractions or both generalized expansions or where an induced step is preceded by a generalized contraction or followed by a generalized expansion. For them also there is an intermediary transition $f$ such that

$$
\begin{aligned}
& f_{i} \circ \frac{f_{i+1}}{f_{i}} \circ \overline{f_{i+1}}=\bar{f} \\
&
\end{aligned}
$$

However, in opposition to the cases of the switching operations (1) to (4), $f$ is not a single step but a horizontal normal form. We will prove this for a vertical composition of arbitrary length, provided the single steps are all of the same kind. The import of this property is explained by the fact that the Switching Lemma in [Lambek 99] preserves equality.

## Lemma 3 (Switching)

Every vertical composition of single steps can be rewritten as a vertical composition of single steps

$$
f_{1} \circ \ldots \circ f_{n}=\left(h_{1} \circ \ldots \circ h_{q}\right) \circ\left(v_{1} \circ \ldots \circ v_{m}\right) \circ\left(g_{1} \circ \ldots \circ g_{p}\right)
$$

such that the $g_{i}$ 's are generalized contractions, the $v_{i}$ 's induced steps and the $h_{i}$ 's generalized expansions. Moreover,

$$
\overline{f_{1}} \circ \ldots \circ \overline{f_{n}}=\left(\overline{h_{1}} \circ \ldots \circ \overline{h_{q}}\right) \circ\left(\overline{v_{1}} \circ \ldots \circ \overline{v_{m}}\right) \circ\left(\overline{g_{1}} \circ \ldots \circ \overline{g_{p}}\right) .
$$

Proof: Omit the induced steps which are identities and use the switching operations (0) to (4).
The horizontal normal forms corresponding to a vertical composition of single steps which are all of the same kind are described thus:

## Definition 3

A normal contraction step is a horizontal composition

$$
u_{0} B_{1} \ldots u_{m-1} B_{m} u_{m}: \Delta_{0} B_{1} \ldots \Delta_{m-1} B_{m} \Delta_{m} \longrightarrow B_{1} \ldots B_{m}
$$

where $u_{k}: \Delta_{k} \longrightarrow 1$ is $\mathbf{1}$ or a horizontal normal form, for $0 \leq k \leq m$.
An normal expansion step is a horizontal composition

$$
o_{0} C_{1} \ldots o_{m-1} C_{m} o_{m}: C_{1} \ldots C_{m} \longrightarrow \Gamma_{0} C_{1} \ldots \Gamma_{m-1} C_{m} \Gamma_{m}
$$

where $o_{k}: 1 \longrightarrow \Gamma_{k}$ is $\mathbf{1}$ or a horizontal normal form, $0 \leq k \leq m$.
A normal vertical step is a horizontal composition

$$
s_{1} \ldots s_{m}: B_{1} \ldots B_{m} \longrightarrow C_{1} \ldots C_{m}
$$

where $s_{k}: B_{k} \longrightarrow C_{k}$ is a simple arrow.
We remark that these normal steps generalize the single steps and are horizontal normal forms.

## Lemma 4

Every vertical composition of generalized contractions $g_{1} \circ \ldots \circ g_{p}: A_{1} \ldots A_{n} \longrightarrow B_{1} \ldots B_{m}$ can be rewritten as a normal contraction step $u_{0} B_{1} \ldots u_{m-1} B_{m} u_{m}$ such that

$$
g_{1} \circ \ldots \circ g_{p}=u_{0} B_{1} \ldots u_{m-1} B_{m} u_{m}
$$

and

$$
\bar{g}_{1} \circ \ldots \circ \bar{g}_{p}=\overline{u_{0}} \overline{B_{1}} \ldots \overline{u_{m-1}} \overline{B_{m}} \overline{u_{m}}
$$

Moreover,

$$
\overline{g_{1} \circ \ldots \circ g_{p}}=\bar{g}_{1} \circ \ldots \circ \bar{g}_{p} .
$$

Proof: Use induction on the length $p$ of the vertical decomposition. Note that

$$
g_{1}=B_{1} \ldots B_{j} \varepsilon_{t} B_{j+1} \ldots B_{m}
$$

where $\varepsilon_{t}: A_{i} A_{k} \longrightarrow 1$ for some $1 \leq i<k \leq n$. By induction hypothesis,

$$
g_{2} \circ \ldots \circ g_{p}=f^{\prime} A_{i} u A_{k} f^{\prime \prime}
$$

where $u: A_{i+1} \ldots A_{k-1} \longrightarrow 1$ is the identity 1 or in normal form and $f^{\prime}: A_{1} \ldots A_{i-1} \longrightarrow B_{1} \ldots B_{j}$ and $f^{\prime \prime}: A_{k+1} \ldots A_{n} \longrightarrow B_{j+1} \ldots B_{m}$ are normal contraction steps. Hence

$$
\begin{array}{rlr}
g_{1} \circ g_{2} \circ \ldots \circ g_{p} & =\left(B_{1} \ldots B_{j} \varepsilon_{t} B_{j+1} \ldots B_{m}\right) \circ\left(f^{\prime} A_{i} u A_{k} f^{\prime \prime}\right) \\
& =f^{\prime}\left(\varepsilon_{t} \circ\left(A_{i} u A_{k}\right)\right) f^{\prime \prime} & \text { by } 2.2 \\
& =f^{\prime} \varepsilon_{t}(u) f^{\prime \prime} . &
\end{array}
$$

Recall that $f^{\prime}=u_{0}{ }^{\prime} B_{1} \ldots u_{j-1}{ }^{\prime} B_{j} u_{j}{ }^{\prime}$ and $f^{\prime \prime}=u_{0}{ }^{\prime \prime} B_{j+1} \ldots B_{m} u_{m-j}{ }^{\prime \prime}$ and define

$$
\begin{aligned}
& u_{l}=u_{l}{ }^{\prime}, \text { for } 0 \leq l \leq j-1 \\
& u_{j}=u_{j}^{\prime} \varepsilon_{t}(u) u_{0}^{\prime \prime} \\
& u_{l}=u_{l-j}{ }^{\prime \prime}, \text { for } j+1 \leq l \leq m
\end{aligned}
$$

As the equalities above hold in all 2-categories, the rest of the assertion follows.

## Lemma 5

Every vertical composition of generalized expansions $h_{1} \circ \ldots \circ h_{q}: C_{1} \ldots C_{m} \longrightarrow D_{1} \ldots D_{m}$ can be rewritten as a normal expansion step $o_{0} D_{1} \ldots o_{m-1} D_{m} o_{m}$ such that

$$
h_{1} \circ \ldots \circ h_{q}=o_{0} D_{1} \ldots o_{m-1} D_{m} o_{m}
$$

and

$$
\overline{h_{1}} \circ \ldots \circ \overline{h_{q}}=\overline{o_{0}} \overline{D_{1}} \ldots \overline{o_{m-1}} \overline{D_{m}} \overline{O_{m}}
$$

Moreover,

$$
\overline{h_{1} \circ \ldots \circ h_{q}}=\bar{h}_{1} \circ \ldots \circ \bar{h}_{q}
$$

Proof: Similar to the case of generalised contractions.

## Lemma 6

If $v_{1} \circ \ldots \circ v_{n}: B_{1} \ldots B_{m} \longrightarrow C_{1} \ldots C_{r}$ is a vertical composition of induced steps, then $r=m$ and there is a normal vertical step $s_{1} \ldots s_{m}$ such that

$$
v_{1} \circ \ldots \circ v_{n}=s_{1} \ldots s_{m} \quad \text { and } \quad \overline{v_{1}} \circ \ldots \circ \overline{v_{n}}=\overline{s_{1}} \ldots \overline{s_{m}}
$$

Moreover,

$$
\overline{v_{1} \circ \ldots \circ v_{n}}=\overline{v_{1}} \circ \ldots \circ \overline{v_{n}}
$$

Proof : First, we remark that the domain and codomain of an induced step are strings of the same length and therefore $r=m$. Now we proceed by induction on $n$, using the switching operation (0) and the distributive laws (2.3)

Lemma 7: The canonical extension ( ) preserves vertical composition.
Proof: By Lemmas 1 and 2 each of $g$ and $f$ separately can be written as a vertical composition of single steps and therefore

$$
g \circ f=f_{1} \circ \ldots \circ f_{n}
$$

respectively

$$
\bar{g} \circ \bar{f}=\overline{f_{1}} \circ \ldots \circ \overline{f_{n}}
$$

Then by Lemmas 3, 4, 5 and 6 , this vertical composition is equal to

$$
f_{1} \circ \ldots \circ f_{n}=o_{0} C_{1} \ldots C_{m} o_{m} \circ s_{1} \ldots s_{m} \circ u_{0} B_{1} \ldots B_{m} u_{m}
$$

respectively

$$
\bar{f}_{1} \circ \ldots \circ \bar{f}_{n}=\overline{o_{0}} \overline{C_{1}} \ldots \overline{C_{m}} \overline{o_{m}} \circ \overline{s_{1}} \ldots \overline{s_{m}} \circ \overline{u_{0}} \overline{B_{1}} \ldots \overline{B_{m}} \overline{u_{m}}
$$

By the distributive laws (2.2) and (2.7), we derive

$$
f_{1} \circ \ldots \circ f_{n}=o_{0} u_{0} s_{1} \ldots s_{m} o_{m} u_{m}
$$

respectively

$$
\overline{f_{1}} \circ \ldots \circ \overline{f_{n}}=\overline{o_{0}} \overline{u_{0}} \overline{s_{1}} \ldots \overline{s_{m}} \overline{o_{m}} \overline{u_{m}}
$$

By definition, the canonical extension commutes with horizontal composition, hence

$$
\overline{f_{1} \circ \ldots \circ f_{n}}=\bar{f}_{1} \circ \ldots \circ \bar{f}_{n}
$$

and thus

$$
\overline{g \circ f}=\bar{g} \circ \bar{f}
$$

This completes the proof of the Theorem in Section 4.

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[^0]:    ${ }^{1}$ (i.e. a path which has no proper extension)

