

## LOD +: Augmenting LOD with Skeletons

Benoit Lange, Nancy Rodriguez

► **To cite this version:**

Benoit Lange, Nancy Rodriguez. LOD +: Augmenting LOD with Skeletons. SIGGRAPH: Special Interest Group on GRAPHics and Interactive Techniques, 2010, Los Angeles, United States. 37th International Conference and Exhibition on Computer Graphics and Interactive Techniques, pp.070, 2010, <<http://www.siggraph.org/s2010/>>. <10.1145/1836845.1836921>. <lirmm-00510207>

**HAL Id: lirmm-00510207**

**<https://hal-lirmm.ccsd.cnrs.fr/lirmm-00510207>**

Submitted on 17 Aug 2010

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# LOD +: Augmenting LOD with skeletons

Benoit LANGE\*  
LIRMM  
Montpellier - France

Nancy RODRIGUEZ †  
LIRMM  
Montpellier - France

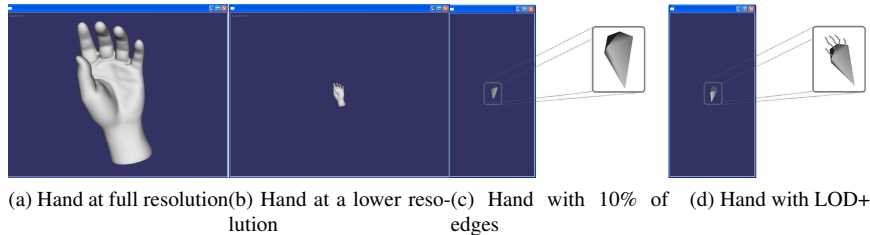


Figure 1: Hand model

## 1 Introduction

Until now computer graphic researchers have tried to solve visualization problems introduced by the size of meshes. Modern tools produce large models and hardware is not able to render them in full resolution. For example, the digital Michelangelo project extracted a model with more than one billion polygons. One can notice hardware has become more and more powerful but meshes have also become more and more complex. To solve this issue, people have worked on many solutions. We can find solutions based on space subdivision, or based on visibility of objects like the use of a Z-buffer. But in 1976, Clark [Clark 1976] introduces the level of detail concept (LOD). The principle of LOD is the construction of several versions of the same 3D model at different resolutions. This is achieved by removing some object features. Luebke provides in [Luebke 1997] a very complete survey of LOD algorithms. The main issue with the simplification is that the mesh does not preserve appearance of the original mesh. Indeed, important features tend to disappear. For example, with the Quadric Error Metrics (QEM) algorithms and the cow mesh, the tail, horn and other characteristic points merge with the mesh at a low resolution. Our approach allows the simplified mesh to preserve important details.

## 2 Our Approach

Our approach is based on Reeb graph theory. A Reeb graph is a data structure that extracts the critical points of a surface and produces a skeleton. This kind of simple structure is commonly used to classify a mesh. Skeletons are also used in mesh animation. The most important use for a Reeb graph is shape analysis ([Tierny et al. 2006]). In fact this solution is the most powerful method to extract object critical points. In our approach we extract the Reeb graph in pre processing. In fact the complexity of Reeb graph extraction is cost expensive. Once the skeleton has been computed, we merge it on the mesh only when the model has been too much degenerated. At present, the solution is based on a threshold but in the future, we hope to find a more adapted metric. The simplification algorithm used is [Garland and Heckbert 1997]. Our solution is called LOD+; it is one of the first solutions to improve LOD low resolution meshes. The first results which allow good shape recognition. The parts of the mesh who are decimate with other algorithms are kept. The main issue of our solution are the bones of the skeleton because

they cross the mesh. We need also to improve skeleton visualization. Thickness of the bones made necessary to define a covering strategy. We have tried some solutions (cylinders and boxes) but this affects performance. It stays one of the main open problems to solve in LOD+.

## 3 Acknowledgment

This research was supported by the URBSIM company and the LRI (Languedoc-Roussillon Incubation). This work is in part supported by VOODOO (2008-2011), a project of ANR and the region of Languedoc Roussillon, France.

## References

- CLARK, J. H. 1976. Hierarchical geometric models for visible surface algorithms. *Commun. ACM* 19, 10, 547–554.
- GARLAND, M., AND HECKBERT, P. S. 1997. Surface simplification using quadric error metrics. In *SIGGRAPH '97: Proceedings of the 24th annual conference on Computer graphics and interactive techniques*, ACM Press/Addison-Wesley Publishing Co., New York, NY, USA, 209–216.
- LUEBKE, D. 1997. A survey of polygonal simplification algorithms.
- REEB, G. 1946. Sur les points singuliers d'une forme de complément intgrable ou d'une fonction numrique. *Comptes Rendus de L'Acadmie des Sances* 222, 847–849.
- TIERNY, J., VANDEBORRE, J.-P., AND DAOUDI, M. 2006. 3d Mesh Skeleton Extraction Using Topological and Geometrical Analyses. In *14th Pacific Conference on Computer Graphics and Applications (Pacific Graphics 2006)*, 85–94.

\*benoit.lange@lirmm.fr

†nancy.rodriguez@lirmm.fr