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Rodrigo Possamai Bastos, Frank Sill Torres, Jean-Max Dutertre, Marie-Lise Flottes, Giorgio Di Natale, et al.. A single built-in sensor to check pull-up and pull-down CMOS networks against transient faults. PATMOS: Power and Timing Modeling, Optimization and Simulation, Sep 2013, Karlsruhe, Germany. pp.157-163, 10.1109/PATMOS.2013.6662169 . lirmm-00968621

HAL Id: lirmm-00968621

<https://hal-lirmm.ccsd.cnrs.fr/lirmm-00968621>

Submitted on 5 Oct 2016

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A Single Built-in Sensor to Check Pull-up and Pull-down CMOS Networks against Transient Faults

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Abstract—This work presents a novel built-in current sensor for detecting transient faults of short and long duration as well as multiple faults in combinational and sequential logic. The sensor is a single mechanism connected to PMOS and NMOS bulks of the monitored logic. With no performance penalty, very competitive results indicate overheads of only 26 % in power consumption and 23 % in area.

Keywords: Built-in current sensors, concurrent detection, fault tolerance, security, soft errors, transient faults

I. INTRODUCTION

Integrated systems based on ultra-deep submicron technologies require higher robustness to natural aging processes or radiation environmental sources [1]. These natural phenomena on integrated circuits can induce transient effects that provoke bit-flips of stored results during the system lifetime. Among the several strategies to detect transient faults caused by radiation or optical sources, Bulk Built-In Current Sensors (BBICS) offer a promising solution that is perfectly suitable for system design flows based on CMOS standard cells of commercial libraries. BBICS have the high detection efficiency of costly fault-tolerance schemes (e.g. duplication with comparison) with the low area and power overheads of less efficient mitigation techniques such as time redundancy approaches. Without impacting on system operating frequency, BBICS deal with transient faults of short and long duration as well as multiple faults. Furthermore, as they closely monitor the zones where the faults arise, an early detection is possible immediately after a fault occurrence, preventing induction and propagation of errors to other clock cycles or system blocks.

All today's BBICS-based strategies [1][2][3][4][5][6] use two different circuits that monitor independently PMOS and NMOS bulk currents from pull-up and pull-down CMOS networks. We present in section III and IV of this paper a new lower area

BBICS version compounded of a single circuit that is able to monitor both CMOS networks. Important preliminary related information regarding built-in current sensors is before discussed in section I.

II. BICS DETECTING TRANSIENT FAULTS

The use of Built-In Current Sensors (BICS) in the bulk for monitoring circuit allows the detection of a wide range of transient faults; such a smart idea was introduced for the first time in [1]. Fig. 1 (a) and (b) illustrate Bulk BICS (BBICS) identifying anomalous transient currents I_{fault} that flow through the junction between a bulk and a reversely biased drain of a disturbed transistor (MOSFETs “off” in Fig. 1). BBICS indeed take advantage of two facts: (1) In fault-free scenarios (i.e. $I_{fault} = 0$) the bulk-to-drain (or drain-to-bulk) current I_B is negligible even if the MOSFET is switching in function of new input stimuli; (2) During transient-fault scenarios, I_{fault} is much higher than the leakage current flowing through the junction. The range of detectable transient faults is easily adjustable by calibrating the size of the transistors that constitute the BBICS. Hence, schemes based on BBICS can be designed to latch a flag of fault indication for abnormal currents within a defined range that represents a risk of resulting in soft errors.

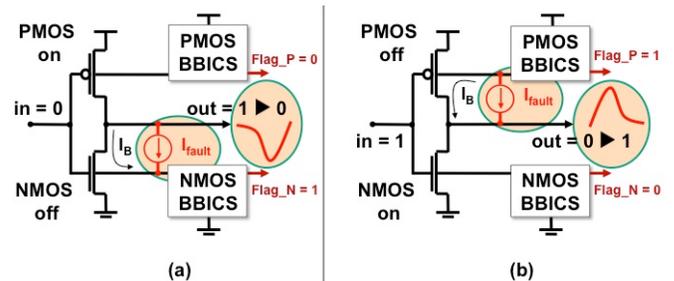


Figure 1. The two classic cases of transient faults in a CMOS inverter perturbed by an anomalous current I_{fault}

III. NEW SINGLE BBICS

The classic BBICS-based strategy is using a pair of sensors (PMOS and NMOS) to monitor pull-up and pull-down networks – e.g. PMOS-BBICS 1 and NMOS-BBICS 1 in Fig. 2 (a). The capacity of each sensor for identifying transient faults is limited to a certain number of monitored transistors. Hence the strategy is also splitting the target system into blocks with the maximum possible number of transistors the sensor is able to monitor. Fig. 2 (a) illustrates an example of system (chains of inverters) divided into two blocks that are monitored by two pairs of BBICS. For the same example, our strategy is otherwise to use single sensors for pull-up and pull-down networks as Fig. 2 (b) shows.

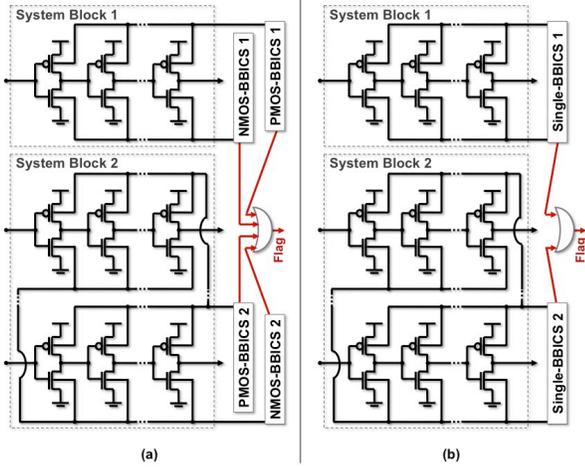


Figure 2. (a) The classic BBICS-based strategy with pairs of BBICS (NMOS and PMOS) monitoring blocks of a system; and (b) Our strategy with the new single BBICS able to check both pull-up and pull-down networks

A. Structure of Sensor

The structure of the new single BBICS presented in this paper takes the high fault-detecting capacity of the sensors proposed in [4] and illustrated in Fig. 3 (a). Moreover, it was optimized from a pair of sensors to a single sensor and, consequently, the area could be significantly reduced as we can see in Fig. 3 (b) compared with Fig. 3 (a) in terms of transistor counting. Low leakage power overheads are met by finding the optimal number of monitored transistors as discussed in section IV. In Fig. 3, W_{min} represents the minimum diffusion width of the transistors, L_{min} is the minimum channel length, and design factors X_n , Y_n , X_p , Y_p , X and Y are used for calibrating the sensor with a desired fault-detecting capacity.

Transistors 5, 6, 7, and 8 in Fig. 3 (b) constitute the latch used to memorize a flag (i.e. output *Flag* at

V_{dd}) in case of a transient fault within a defined range of current that temporally perturbs the monitored pull-up or pull-down network. In addition, the latch transistors are responsible for amplifying the anomalous transient currents coming from node *NMOS_Bulk* or going to node *PMOS_Bulk* of monitored blocks. Factors X and Y allow increasing the gain of amplification and, thus, configuring the sensor with higher fault-detecting capacity. Transistors 11 and 12 are used to set the sensor in sleep-mode when the system is left on standby (i.e. signal *Sleep_Mode* at V_{dd}). It leads to zero the offset on the bulk voltage of the monitored block, and so the sub-threshold leakage power consumption is significantly reduced.

B. Mode of Operation

In fault-free conditions and inactive sleep mode (i.e. *Sleep_Mode* at gnd), the proposed structure in Fig. 3 (b) has in theory *NMOS_Bulk* at gnd level and *PMOS_Bulk* at V_{dd} . Signal *Flag* is at gnd ; *node1* at V_{dd} , and transistors 1, 3, 4, 10, 11, and 12 are in off-state. Further, as transistors 2 and 9 are in on-state, they impose, in reality, on *NMOS_Bulk* and *PMOS_Bulk* a small voltage drop.

In case of a transient fault in the pull-up network of the monitored block, *PMOS_Bulk* acts as a current sink, i.e. a transient current flows from *node1* to *PMOS_Bulk* through transistor 9. Thereby the voltage of *node1* decreases, leading the inverter formed by transistor 6 and 5 to flip and signal *Flag* to change from gnd to V_{dd} . As consequence, the other inverter (i.e. transistor 7 and 8) also switches forcing *node1* to gnd even after the transient fault has ceased. Moreover, it activates transistors 10 and 1 in order to set the normal operation levels for *PMOS_Bulk* and *NMOS_Bulk* (i.e. V_{dd} and gnd) during such a state of fault indication at *Flag*. As soon as this flag is processed by higher instances of the system, it must be reset (i.e. input *Reset* at V_{dd}) to be able to detect again other transient faults.

If a fault happens in the pull-down network of the monitored block, a transient current flows through transistor 2 coming from *NMOS_Bulk* and, consequently, the same procedure described above is performed to register an indication of fault (i.e. signal *Flag* from gnd to V_{dd}). Note that if other transient fault occurs simultaneously in pull-up network, the single BBICS is able to accomplish the memorization of a flag since the sense of the

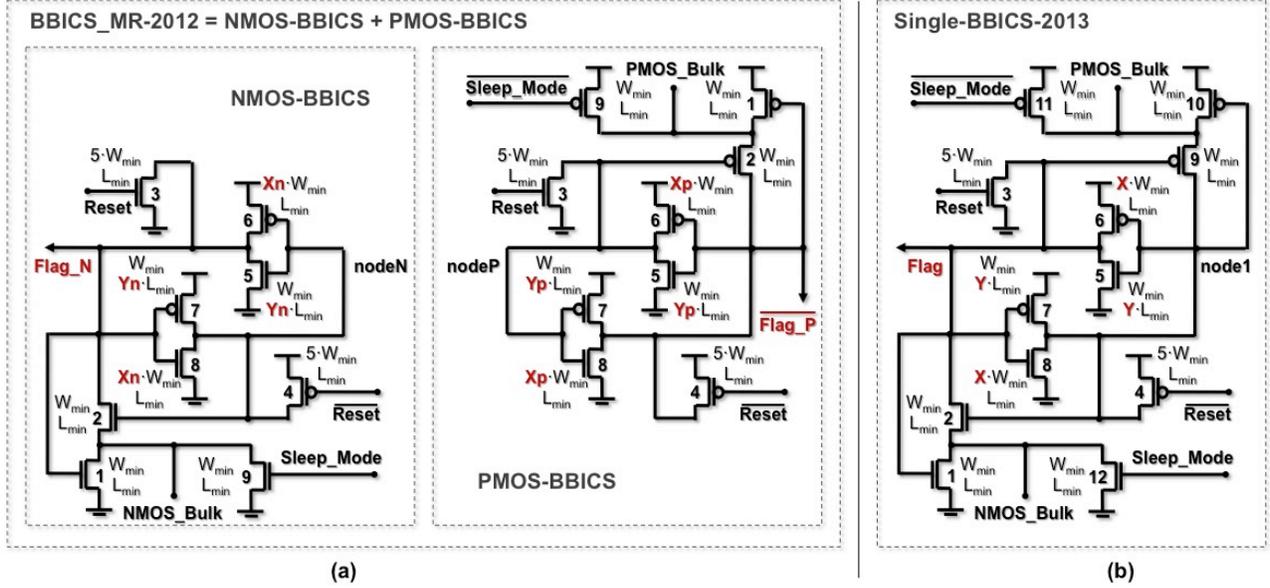


Figure 3. (a) Structures of a BBICS pair (NMOS and PMOS) proposed in [4]; and (b) the structure of our new single BBICS

positive feedback is the same for both fault events. On the contrary, no new transient fault can be detected when a flag of fault is latched or during the reset of the sensor.

IV. ANALYSIS OF SIMULATION RESULTS

The proposed new structure named in Fig. 3 (b) as *Single-BBICS-2013* was designed, analyzed, and compared with previous version labeled in Fig. 3 (a) as *BBICS MR-2012*. Transistor-level sensor versions were designed based on predictive 32-nm CMOS technology [7] in nominal conditions and using a V_{dd} of 0.9 V, W_{min} of 64 nm, and L_{min} of 32 nm. In order to test different sensor versions, N chain of 10 inverters, such as system block 2 with $N = 2$ in Fig. 2, were used as a reference circuit under protection. Therefore, either just one pair of BBICS (i.e. *BBICS MR-2012* version) or only one *Single-BBICS-2013* monitors a reference circuit of N chains. All inverters of the chains were sized with minimum dimensions (i.e. $L_p=L_n=L_{min}$; $L_n=W_{min}$; and $W_p=2.5 \cdot W_{min}$).

The sensors were calibrated using the method proposed in [1]. It allows finding, at design time and in function of factor X , the smallest factor Y that produces a sensor with the capacity of detecting a certain minimum transient-fault profile, which here is defined as a double exponential current source I_{fault} with duration of 50ps (measured at the half amplitude of the current) that results in a transient

voltage amplitude of 50% of V_{dd} . In addition, we set a constraint to search the design factors: the sensors must have a response time lesser than 1 ns – i.e. they must indicate a flag at the maximum 1 ns after the beginning of the transient fault. Different *BBICS_MR-2012* and *Single-BBICS-2013* versions were created varying factor X and finding the smallest factor Y that meets the response time constraint to monitor a reference circuit. These optimal design factors allow identifying the best trade-off between power and area and, consequently, the optimal sensor versions. More details about it will be described in the final version of this paper.

A. The Optimal Number of Monitored Transistors

Fig. 4 presents the overhead results for the optimal sensor versions as well as the power reductions whether the sleep mode is active (i.e. system on standby). We can see in Fig. 4 that there are minimum points on the curves for sleep mode in off-state. Therefore, it allows finding the optimal number of monitored chains. Observe in Fig. 4 that, after 6 chains, lower the number of chains, higher the overheads since there are less transistors compounding the reference circuit. The optimal number of chains for both BBICS types is hence 6, and their design factors are $X_n=2$, $Y_n=6.2$, $X_p=2$, $Y_p=10.9$, $X=3$ and $Y=13.7$. As the pull-up network is always larger than the pull-down network in order to compensate the slower mobility of PMOS

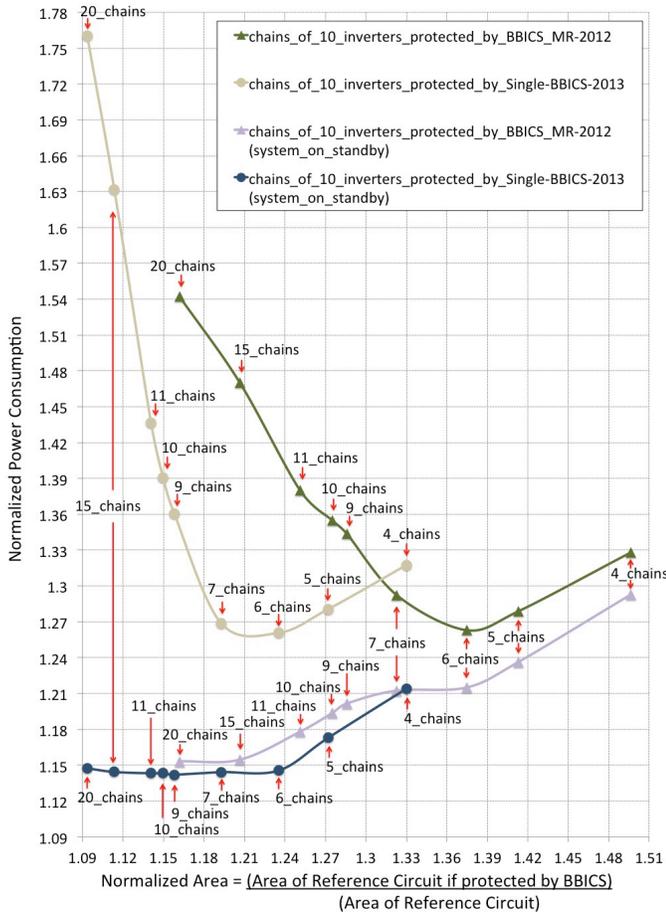


Figure 4. Normalized power consumption and area for several reference circuits monitored by the optimal sensor versions

transistors, the design factor Y_p has to be greater than Y_n . Hence, the design factors of *Single-BBICS-2013* are also greater. Further, as a single sensor is used to monitor both networks, its structure requires higher gain of amplification to balance the higher load on *node1*. Consequently, the offset on the bulk voltage is also higher, as seen in Fig. 5, leading to greater static power consumption especially due to the offset on PMOS bulk voltage. On the other hand, as the number of transistors is lower by using *Single-BBICS-2013*, the power overhead achieves similar results than *BBICS_MR-2012* (about 26 %) and the area offset around 23 % against 38 % of *BBICS_MR-2012*. Moreover, if sleep mode is active, the power penalty is 15 % against 21 % of *BBICS_MR-2012*. One could argue that an offset on bulk voltage would reproduce noticeably change on threshold voltages of monitored gates and, thus, their timing characteristics would be altered. However simulation results show that the modifications in rise and fall time, and rise and fall delay of monitored

inverters are negligible. Therefore, no performance penalty is observed. Otherwise, as the sub-threshold leakage current is an exponential function of the threshold voltage, the static power consumption of monitored gates is significantly increased by around 17%. If sleep mode is active, the static power overhead is 7%.

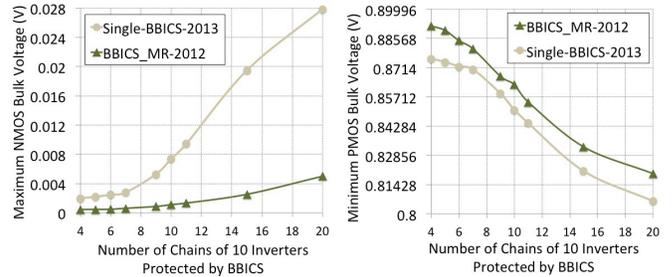


Figure 5. Maximum NMOS bulk voltage and Minimum PMOS bulk voltage in function of the number of chains of 10 inverters protected by BBICS

V. CONCLUSIONS

This paper proposes a new BBICS presenting lower area than previous version and similar power overhead. In addition, it achieves lower sleep-mode power. With no performance penalty, this work allows identifying the optimal design factors of the sensor as well as the optimal number of monitored transistors to obtain the best trade-off between area and power. Furthermore, the results show that the offset on the NMOS bulk voltage is negligible for the optimal sensor versions. Ongoing works are the fabrication of a prototype and the validation of the approach using a laser beam to inject transient faults.

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