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Constraint Programming for Mining Borders of Frequent Itemsets

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Abstract
Frequent itemset mining is one of the most studied tasks in knowledge discovery. It is often reduced to mining the positive border of frequent itemsets, i.e. maximal frequent itemsets. Infrequent itemset mining, on the other hand, can be reduced to mining the negative border, i.e. minimal infrequent itemsets. We propose a generic framework based on constraint programming to mine both borders of frequent itemsets. One can easily decide which border to mine by setting a simple parameter.

1 Introduction
Data mining is the art of discovering knowledge from databases. It includes the discovering of frequent itemsets, association rules [Agrawal et al., 1994; Han et al., 2000], rare itemsets [Szathmary et al., 1994; Liu et al., 1999], sequence patterns [Agrawal and Srikant, 1995], emerging patterns [Dong and Li, 1999], and many other tasks. For many data mining problems, the frequency represents an important metric. Given a frequency threshold \(s\) over a transaction dataset, frequent itemsets are those present in at least \(s\) transactions. Itemsets present in less than \(s\) transactions are called infrequent (or rare). The number of frequent/infrequent itemsets can be huge, making it hard even to print the result. Hence, we often reduce the problem of mining frequent or infrequent itemsets to the problem of mining the borders. The positive border is the set of frequent itemsets with only infrequent supersets, i.e. Maximal Frequent Itemsets (MFIs). The negative border is the set of infrequent itemsets with only frequent subsets, i.e. Minimal Infrequent Itemsets (MIIs). The subsets of the MFIs and the supersets of the MIIs represent the frequent and infrequent itemsets, respectively.

Several techniques have been introduced for mining MFIs [Burdick et al., 2001; Gouda and Zaki, 2001; Uno et al., 2004], or MIIs [Szathmary et al., 2007; Haglin and Manning, 2007; Szathmary et al., 2012]. Despite an obvious duality between MFIs and MIIs, very few papers propose a single framework for mining both MFIs and MIIs. In [Mannila and Toivonen, 1997; Boros et al., 2003; Nourine and Petit, 2012], inferring MFIs from the set of MIIs and vice versa (or also called the dualization) is reduced to computing the minimal transversals of a hypergraph [Berge, 1984]. In fact, MIIs correspond to the minimal transversals of the hypergraph constructed by the complements of the set of MFIs.

In a recent line of work, researchers have taken advantage of the flexibility of constraint programming to model various data mining problems [De Raedt et al., 2008; Khiari et al., 2010; Lazaar et al., 2016; Schaus et al., 2017; Bessiere et al., 2018]. In terms of CPU time, constraint programming-based methods have not yet competed with ad hoc algorithms. However, their flexibility allows the modeling of complex user queries without revising the solving process.

In this paper we propose a generic parameterized model allowing the user to decide which border to mine (i.e., MFIs or MIIs). For this model we need to define two new global constraints: (1) FREQUENTSUBS for mining itemsets having only frequent subsets, and (2) INFREQUENTSUPERS for mining itemsets having only infrequent supersets. We provide a polynomial domain consistency propagator for each of these two constraints. We then address the issue of mining borders in the presence of other constraints. As noticed in [Bonchi and Lucchese, 2004], mining borders under additional constraints can lead to the loss of solutions. This can happen with maximal/minimal borders, but also with closed itemsets or generator itemsets. We prove that it is coNP-hard to find maximal/minimal itemsets among those satisfying a set of additional constraints. This implies that there does not exist any CSP representing the problem of finding maximal/minimal itemsets under additional constraints, unless coNP \(\subseteq NP\). This is an a posteriori justification of the "multi-shot" approaches, such as the one presented in [Negrevergne et al., 2013].

The paper is organized as follows. Section 2 gives some background material. In Section 3 we give a generic model for mining MFIs or MIIs. We define the new global constraints FREQUENTSUBS and INFREQUENTSUPERS and we present their propagators. Section 4 analyzes the problem of mining constrained MFIs or MIIs. We present some empirical results in Section 5. Finally, we conclude in Section 6.
<table>
<thead>
<tr>
<th>transaction</th>
<th>Items</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t_1$</td>
<td>A B D E</td>
</tr>
<tr>
<td>$t_2$</td>
<td>A C</td>
</tr>
<tr>
<td>$t_3$</td>
<td>A B C E</td>
</tr>
<tr>
<td>$t_4$</td>
<td>B C E</td>
</tr>
<tr>
<td>$t_5$</td>
<td>A B C E</td>
</tr>
</tbody>
</table>

Table 1: Dataset

2 Background

2.1 Itemsets

Let $I = \{1, \ldots, n\}$ be a set of $n$ item indices and $T = \{1, \ldots, m\}$ a set of $m$ transaction indices. An itemset $P$ is a non-empty subset of $I$. $D = \{t_1, \ldots, t_m\}$ is the transactional dataset, where for all $i \in T$, $t_i$ is an itemset. The cover of an itemset $P$, denoted by $\text{cover}(P)$, is the set of transactions containing $P$. The frequency of an itemset $P$ is the cardinality of its cover i.e. $\text{freq}(P) = |\text{cover}(P)|$. Let $s$ be some given constant called a support threshold. The itemset $P$ is frequent if $\text{freq}(P) \geq s$. $P$ is infrequent (or rare) if $\text{freq}(P) < s$. We now define the two main notions used in this paper.

Definition 1 (Maximal Frequent Itemset (MFI)) An itemset is an MFI if it is frequent and all its proper supersets are infrequent.

Definition 2 (Minimal Infrequent Itemset (MII)) An itemset is an MII if it is infrequent and all its proper subsets are frequent.

In [Mannila and Toivonen, 1997] MFIs and MIIs are referred to as positive and negative border respectively. MFIs are closed and MIIs are a generator itemset. We define closed and generator itemsets.

Definition 3 (Closed itemset [Pasquier et al., 1999]) An itemset $P$ is closed if and only if there does not exist any itemset $Q \supseteq P$ such that $\text{freq}(Q) = \text{freq}(P)$.

Definition 4 (Generator [Bastide et al., 2000]) A generator is an itemset $P$ such that there does not exist any itemset $Q \subseteq P$ such that $\text{freq}(Q) = \text{freq}(P)$.

Example 2.1 With $s = 3$, the dataset in Table 1 has MFIs = \{ABE, AC, BCE\} and MIIs = \{ABC, ACE, D\}.

2.2 Constraint Programming (CP)

A CP model specifies a set of variables $X = \{x_1, \ldots, x_n\)$, a set of domains $\text{dom} = \{\text{dom}(x_1), \ldots, \text{dom}(x_n)\}$, where $\text{dom}(x_i)$ is the finite set of possible values for $x_i$, and a set of constraints $C$ on $X$. A constraint $c_j \in C$ is a relation that specifies the allowed combinations of values for its variables $\text{var}(c_j)$. An assignment on a set $Y \subseteq X$ of variables is a mapping from variables in $Y$ to values, and a valid assignment is an assignment where all values belong to the domain of their variable. A solution is an assignment on $X$ satisfying all constraints. Constraint programming is the art of writing problems as CP models and solving them by finding solutions. Constraint solvers typically use backtracking search to explore the search space of partial assignments. At each assignment, constraint propagation algorithms (aka, propagators) prune the search space by enforcing local consistency properties such as domain consistency.

A constraint $c$ on $\text{var}(c)$ is domain consistent (DC) if and only if, for every $x_i \in \text{var}(c)$ and every $d_j \in \text{dom}(x_i)$, there is a valid assignment satisfying $c$ such that $x_i = d_j$. Global constraints are constraints defined by a relation on any number of variables. The constraint AllDifferent, specifying that all its variables must take different values is an example of global constraint (see [Rossi et al., 2006]).

**Example 2.2** Consider the following instance of a CP model. $X = \{x_1, x_2, x_3\}$, $\text{dom}(x_1) = \{0, 2\}$, $\text{dom}(x_2) = \{0, 2, 4\}$, $\text{dom}(x_3) = \{1, 2, 3, 4\}$, and $C = \{x_1 \leq x_2, x_1 + x_2 = x_3\}$. Value 4 for $x_2$ will be removed by DC because of constraint $x_1 \leq x_2$. Values 1 and 3 for $x_3$ will be removed by DC because of constraint $x_1 + x_2 = x_3$. This CP model admits the two solutions $(x_1 = 2, x_2 = 0, x_3 = 2)$ and $(x_1 = 2, x_2 = 2, x_3 = 4)$.

3 A Generic CP Model for Mining Borders

We present a CP model, $\text{MODEL}_{D,s,b}$, for mining MFIs or MIIs. $\text{MODEL}_{D,s,b}$ uses a vector $x$ of $n$ Boolean variables, where $x_i$ represents the presence of the item $i$ in the itemset. We will use the following notations:

- $x^{-1}(1) = \{i \in I \mid \text{dom}(x_i) = \{1\}\}$
- $x^{-1}(0) = \{i \in I \mid \text{dom}(x_i) = \{0\}\}$
- $x^{-1}() = \{i \in I \mid i \notin x^{-1}(1) \cup x^{-1}(0)\}$

$$\text{MODEL}_{D,s,b}(x) = \begin{cases} & \text{FREQUENTSUBS}_{D,s}(x) \quad (1) \\ & \text{INFREQUENTSUPERS}_{D,s}(x) \quad (2) \\ & b \iff \text{FREQUENT}_{D,s}(x) \quad (3) \end{cases}$$

where (1) is a global constraint that holds if and only if the itemset $x^{-1}(1)$ has only frequent supersets w.r.t $s$, (2) is a global constraint that holds if and only if the itemset $x^{-1}(1)$ has only infrequent supersets w.r.t $s$ and the Boolean parameter $b$ reifies the global constraint FREQUENT (3). $\text{FREQUENT}_{D,s}$ holds if and only if $x^{-1}(1)$ is frequent w.r.t $s$. We prove that $\text{MODEL}_{D,s,b}$ is a correct model for mining MFIs or MIIs.

**Theorem 1** The set of solutions to $\text{MODEL}_{D,s,b}$ corresponds to the set of MFIs if $b = \text{true}$, the set of MIIs otherwise.

**Proof.** We first prove that MFIs and MIIs always satisfy constraints (1) and (2). All supersets of an MFI are infrequent, thus satisfying (2). Because an MFI is frequent, all its proper subsets are frequent, thus satisfying (1). An MII has only infrequent subsets, thus satisfying (1). Because an MII is infrequent, it has only infrequent supersets, thus satisfying (2). Hence, all MFIs and all MIIs satisfy constraints (1) and (2).

We now prove that a solution of $\text{MODEL}_{D,s,b}$, can only be an MFI or an MII depending on the value of $b$. A solution of $\text{MODEL}_{D,s,b}$ can only be frequent (i.e., $b = \text{true}$) or infrequent (i.e., $b = \text{false}$). If it is frequent then it is an MFI (see Definition 1). Otherwise it is an MII (see Definition 2).
Example 3.1 The lattice in Figure 1 displays the set of itemsets satisfying the constraints FREQUENTSUBS and INFREQUENTSUPERS on the dataset of Table 1 with \( s = 3 \). The intersection between both sets is the set \( MFIs \cup MII s \).

We can then use MODEL to mine either MFI s or MII s by simply setting \( b \) to true or false. We now define the global constraints FREQUENTSUBS and INFREQUENTSUPERS and we propose propagators.

### 3.1 The Global Constraint FREQUENTSUBS

We present the new global constraint \( \text{FREQUENT} \) used to mine itemsets that have only frequent subsets.

**Definition 5 (FREQUENTSUBS)** Let \( x \) be a vector of Boolean variables, \( s \) a support threshold and \( D \) a dataset. The global constraint \( \text{FREQUENT}_{D, s}(x) \) holds if and only if \( \forall p \subseteq x^{-1}(1), \text{Freq}(p) \geq s \).

**Algorithm.** The propagator for the global constraint \( \text{FREQUENT} \) is presented in Algorithm 1. Algorithm 1 takes as input the variables \( x \) and the support threshold \( s \). Algorithm 1 starts by computing the cover of the itemset \( x^{-1}(1) \) and stores it in \( \text{cover} \) (line 4). Then, for each item \( j \in x^{-1}(1) \), Algorithm 1 computes the cover of the subset \( x^{-1}(1) \setminus \{j\} \), and stores it in \( \text{cov}[j] \) (line 6). If \( x^{-1}(1) \setminus \{j\} \) is infrequent then \( x^{-1}(1) \) is not a solution and we return a failure (line 7). Algorithm 1 must then remove items \( i \) that cannot belong to a solution containing \( x^{-1}(1) \). To do that, we first test if the itemset \( x^{-1}(1) \) is infrequent (line 8). If so, we remove 1 from \( \text{dom}(x_i) \) for all \( i \in x^{-1}(s) \) (lines 9-10) because the itemset \( x^{-1}(1) \cup \{i\} \) has an infrequent subset \( x^{-1}(1) \) for every \( i \in x^{-1}(s) \). Otherwise, for every item \( i \) in \( x^{-1}(s) \) we test if the itemset \( x^{-1}(1) \cup \{i\} \) is infrequent (line 12). If so, it can have infrequent subsets. Thus, for every item \( j \in x^{-1}(1) \), we test if the size of the cover of \( x^{-1}(1) \cup \{i\} \setminus \{j\} \) (i.e., \( \text{cov}[j] \setminus \text{cover}(i) \)) is less than \( s \) (line 14). If so, we remove \( i \) from the possible items, that is, we remove 1 from \( \text{dom}(x_i) \) and break the loop (line 15).

**Theorem 2** The propagator in Algorithm 1 enforces domain consistency on the constraint \( \text{FREQUENT} \).

**Algorithm 1: Propagator for \( \text{FREQUENT} \)**

1. **In:** \( s \): support threshold;
2. **InOut:** \( x = \{x_1 \ldots x_n\} \): Boolean item variables;
3. **begin**
4. \( \text{cover} \leftarrow \text{cover}(x^{-1}(1)) \);
5. **foreach** \( j \in x^{-1}(1) \) **do**
6. \( \text{cov}[j] \leftarrow \text{cover}(x^{-1}(1) \setminus \{j\}) \);
7. **if** \( |\text{cov}[j]| < s \) **then** return failure;
8. **if** \( |\text{cover}| < s \) **then**
9. **foreach** \( i \in x^{-1}(s) \) **do**
10. \( \text{dom}(x_i) \leftarrow \text{dom}(x_i) \setminus \{1\} \);
11. **foreach** \( i \in x^{-1}(s) \) **do**
12. **if** \( |\text{cover} \cap \text{cover}(i)| < s \) **then**
13. **foreach** \( j \in x^{-1}(1) \) **do**
14. **if** \( |\text{cov}[j] \cap \text{cover}(i)| < s \) **then**
15. \( \text{dom}(x_i) \leftarrow \text{dom}(x_i) \setminus \{1\} \); break;

**Proof.** We first prove that if \( \text{FREQUENT} \) admits a solution, \( x^{-1}(1) \) is necessarily one of them. Suppose there is a solution and \( x^{-1}(1) \) is not one of them. This means that there exists a superset of \( x^{-1}(1) \) which has all its subsets frequent. \( x^{-1}(1) \) is one of these subsets. Thus, all subsets of \( x^{-1}(1) \) are frequent and \( x^{-1}(1) \) is solution too, which contradicts the assumption. We now prove that Algorithm 1 returns failure if and only if \( \text{FREQUENT} \) does not admit any solution. We know that \( \text{FREQUENT} \) has no solution if and only if \( x^{-1}(1) \) is not solution. \( x^{-1}(1) \) is not solution if and only if it has an infrequent subset \( x^{-1}(1) \setminus \{j\} \) for some \( j \in x^{-1}(1) \). In such a case the test in line 7 is true and failure is returned. If \( \text{FREQUENT} \) admits solutions, \( x^{-1}(1) \) is a support for \( x_i = 0 \), for all \( i \in x^{-1}(s) \). As a result, Algorithm 1 does not need to check consistency of value 0 for any variable.

We now prove that Algorithm 1 prunes value 1 from \( \text{dom}(x_i) \) exactly when \( i \) cannot belong to a solution containing \( x^{-1}(1) \). Suppose value 1 of \( x_i \) is pruned by Algorithm 1. This means that the test in line 8 (or line 14) was true, that is, there exists a subset of \( x^{-1}(1) \cup \{i\} \) which is infrequent. Thus, by definition, \( x^{-1}(1) \cup \{i\} \) does not belong to any solution. Suppose now that value 1 of \( x_i \) is not pruned. From lines 8 and 14, we deduce that there does not exist any infrequent subset of \( x^{-1}(1) \cup \{i\} \). Thus \( x^{-1}(1) \cup \{i\} \) is a solution and value 1 of \( x_i \) is domain consistent. 

**Theorem 3** Given a transaction dataset \( D \) of \( n \) items and \( m \) transactions, Algorithm 1 has an \( O(n^2 \times m) \) time complexity.

**Proof.** Computing the size of the cover of an itemset is in \( O(n \times m) \). Line 5 is called at most \( n \) times, leading to a time complexity in \( O(n^2 \times m) \). The time complexity of lines 8-10 is bounded above by \( n \). The test at line 13 is done at most \( n^2 \) times. The cover \( x^{-1}(1) \cup \{i\} \setminus \{j\} \) at line 13 is computed in \( O(m) \) thanks to the \( \text{cov} \) data structure. Thus, the time complexity of lines 9-14 is bounded above by \( n^2 \times m \). As a result, Algorithm 1 has an \( O(n^2 \times m) \) time complexity. 

\[ \Box \]
Algorithm 2: Propagator for INFREQUENTSUPERS

1. In: $s$: support threshold;
2. InOut: $x = \{x_1 \ldots x_n\}$: Boolean item variables;
3. begin
4.   cover ← $\text{cover}(x^{-1}(1) \cup x^{-1}(s))$;
5.   if $|\text{cover}| \geq s$ then
6.     foreach $j \in x^{-1}(0)$ do
7.         if $|\text{cover} \cap \text{cover}(j)| \geq s$ then
8.             return failure;
9.     foreach $i \in x^{-1}(s)$ do
10.    cover2 ← $\text{cover}(x^{-1}(1) \cup x^{-1}(s) \setminus \{i\})$;
11.   if $|\text{cover2}| \geq s$ then
12.      foreach $j \in (x^{-1}(0) \cup \{i\})$ do
13.         if $|\text{cover2} \cap \text{cover}(j)| \geq s$ then
14.             $\text{dom}(x_i) \leftarrow \text{dom}(x_i) \setminus \{0\}$; break;

3.2 The Global Constraint INFREQUENTSUPERS

We present the new global constraint INFREQUENTSUPERS used to mine itemsets that have only infrequent supersets.

Definition 6 (INFREQUENTSUPERS) Let $x$ be a vector of Boolean variables, $s$ a support threshold and $D$ a dataset. The global constraint $\text{INFREQUENTSUPERS}_{D,s}(x)$ holds if and only if $\forall p \ni x^{-1}(1), \text{freq}(p) < s$.

Algorithm. The propagator for the global constraint INFREQUENTSUPERS is presented in Algorithm 2. Algorithm 2 takes as input the variables $x$ and the support threshold $s$. Algorithm 2 starts by computing cover, the cover of the largest possible itemset, $x^{-1}(1) \cup x^{-1}(s)$ (line 4). If such an itemset has a frequent superset (line 7) then no itemset containing $x^{-1}(1)$ can be a solution and we return failure (line 8). Algorithm 2 must then remove value 0 from $\text{dom}(x_i)$ if the absence of the item $i$ can lead to an itemset that has a frequent superset. To do that, for every free item $i$ (line 9), Algorithm 2 computes cover2, the cover of the largest itemset not containing the item $i$, i.e. $x^{-1}(1) \cup x^{-1}(s) \setminus \{i\}$ (line 10). If $x^{-1}(1) \cup x^{-1}(s) \setminus \{i\}$ is frequent (line 11), it could have a frequent superset. Thus, for every item $j$ in $x^{-1}(0) \cup \{i\}$ we test whether the itemset $x^{-1}(1) \cup x^{-1}(s) \setminus \{i\} \cup \{j\}$ is frequent (line 13). If so, we remove 0 from $\text{dom}(x_i)$ and break the loop (line 14).

Theorem 4 The propagator in Algorithm 2 enforces domain consistency on the constraint INFREQUENTSUPERS.

Proof. We first prove that if INFREQUENTSUPERS admits a solution, $x^{-1}(1) \cup x^{-1}(s)$ is necessarily one of them. Suppose there is a solution and $x^{-1}(1) \cup x^{-1}(s)$ is not one of them. This means that there exists a subset of $x^{-1}(1) \cup x^{-1}(s)$ which has all its supersets infrequent. $x^{-1}(1) \cup x^{-1}(s)$ is one of these supersets. Thus, all supersets of $x^{-1}(1) \cup x^{-1}(s)$ are infrequent and $x^{-1}(1) \cup x^{-1}(s)$ is solution too, which contradicts the assumption. We now prove that Algorithm 2 returns failure if and only if INFREQUENTSUPERS does not admit any solution. We know that if INFREQUENTSUPERS has solutions, $x^{-1}(1) \cup x^{-1}(s)$ is one of them. $x^{-1}(1) \cup x^{-1}(s)$ is not solution if and only if it has a frequent superset. In such a case the test in line 7 is true for some $j$ in $x^{-1}(0)$ and failure is returned. If INFREQUENTSUPERS has solutions, $x^{-1}(1) \cup x^{-1}(s)$ is a support for $x_i = 1$, for all $i \in x^{-1}(s)$. As a result, Algorithm 2 does not need to check consistency of value 1 for any variable.

We now prove that Algorithm 2 prunes 0 from $\text{dom}(x_i)$ exactly when $i$ belongs to all solutions containing $x^{-1}(1)$. If the test in line 13 is true this means that with $x_i = 0$ we get itemsets having at least a frequent superset. Hence, 0 must be pruned from $\text{dom}(x_i)$. Suppose now that the test in line 13 is false for all $j$. $x^{-1}(1) \cup x^{-1}(s) \setminus \{i\}$ has only infrequent supersets and $x_i = 0$ is domain consistent.

Theorem 5 Given a transaction dataset $D$ of $n$ items and $m$ transactions, Algorithm 2 has an $O(n^3 \times m)$ time complexity.

Proof. Computing the cover of $x^{-1}(1) \cup x^{-1}(s)$ in line 4 is in $O(n \times m)$. The loop in line 6 computes the cover of $x^{-1}(1) \cup x^{-1}(s) \setminus \{j\}$ in $O(m)$ using the already computed cover of $x^{-1}(1) \cup x^{-1}(s)$ (i.e., cover). As a result the worst case time complexity of lines 4-8 is in $O(n \times m)$. Similarly, the time complexity of lines 10-14 is bounded above by $n \times m$. Lines 10-14 are called at most $n$ times, leading to a time complexity in $O(n^2 \times m)$.

It is worth noticing the duality between Algorithm 1 and Algorithm 2. Algorithm 1 removes value 1 from $\text{dom}(x_i)$ if including the item $i$ leads to an itemset having an infrequent subset. Algorithm 2 removes value 0 from $\text{dom}(x_i)$ if excluding the item $i$ necessarily leads to itemsets having a frequent superset. This duality is not totally obvious at a first glance because Algorithm 1 requires the cov data structure to have its good time complexity whereas Algorithm 2 does not need it. The reason is that Algorithm 1 computes the covers of subsets that we cannot derive from the cover of their supersets whereas Algorithm 2 computes covers of supersets that can be obtained by simple bitwise operation on their subsets.

4 On Constrained Borders

As pointed out in [Bonchi and Lucchese, 2004], constraints can interfere with closedness (or maximality) when they are not monotone. Likewise, constraints can interfere with minimality when they are not anti-monotone. Hence, existing "one-shot" CP approaches can miss solutions because they look for maximal/minimal itemsets that in addition satisfy constraints (see [Lazar et al., 2016]), whereas we are usually interested in itemsets that are maximal (or minimal) among those satisfying the constraints. In this section we prove that deciding whether a frequent itemset is maximal or closed or minimal among those satisfying the constraints is coNP-complete. This means that finding maximal/closed/minimal itemsets among those satisfying a set of constraints is coNP-hard. It is a proof that it is not possible to solve this problem using a single CSP (unless coNP $\subseteq$ NP). This validates "multi-shot" approaches [Negrevergne et al., 2013].

Theorem 6 Given a dataset $D$ on a set of items $I$ and a set $C$ of user's constraints, deciding whether an itemset is maximal/closed among those satisfying $C$ is coNP-complete.
Proof. Membership. Given an itemset $P$, a witness to its non-maximality/closedness is an itemset $P' \supseteq P$ that is frequent, satisfies $C$, and in the case of closedness has the same frequency as $P$. Checking that $P'$ is frequent and checking that it has the same frequency as $P$ is linear in $|D|$. Checking that $P'$ satisfies $C$ requires the polynomial check of the $C$ constraints. Hence, the “no” answer admits a polynomial certificate, and so deciding maximality or closedness is in coNP.

Completeness. We reduce co3COL, which is coNP-complete, to the problem of deciding whether an itemset is maximal/closed. We want to decide whether a connected graph $G = (V, E)$ is non colorable with three colors. We build the dataset $D$ on the set $I = \{a_1, \ldots, a_n, b_1, \ldots, b_n\}$ of items, where $n = |V|$. The pair $(a_i, b_i)$ of items will represent the vertex $i$ in $V$. $D$ contains the single transaction $(1, \ldots, 1)$ and the frequency threshold $s$ is set to $|T|/2$.

As in all CP models for itemset mining, there is a Boolean variable for each item. The standard semantics is that each variable for each item. The frequency of user’s constraints, deciding whether an itemset is minimal/generator among those satisfying $C$ is equivalent to deciding whether $G$ is non 3-colorable.

Corollary 1 Given a dataset $D$ on a set of items $I$ and a set $C$ of user’s constraints, finding an itemset that is maximal/closed/minimal/generator among those satisfying $C$ is coNP-hard.

5 Experiments

We made several experiments to compare our CP model MODELD,s,b to the state of the art approaches.

5.1 Experimental Protocol

The implementation of MODELD,s,b and its constraint propagators were carried out in the Oscar solver using Scala (https://gitbucket.org/oscarnlib/oscar). The code is publicly available at git.euric.fr/belaid/cp4borders. All experiments were conducted on an Intel core i7, 2.2Ghz with a RAM of 8Gb and a timeout of one hour. MODELD,s,b is denoted by CP4MFI (resp. CP4MII) when $b = 1$, i.e. mining MFIs, (resp. $b = 0$, mining MIIs). We used the global constraint COVERSIZE to encode the constraint (3) in MODELD,s,b. COVERSIZE$_P(x,p)$ holds if and only if $p = \lceil \text{cover}(x^{-1}(1)) \rceil$ [Schaus et al., 2017]. We enforce frequency by simply adding the constraint $p \geq s$ and infrequency by adding $p < s$. The propagator of COVERSIZE enforces DC on the frequency, but it does not on the infrequency. We have assessed the quality of the COVERSIZE encoding of infrequency by comparing to a propagator that enforces DC on the infrequency. We observed that the number of additional nodes explored with the COVERSIZE encoding was marginal and the CPU time was better. We thus use the propagator of COVERSIZE in all our experiments. As an MFI is a closed itemset and an MII is a generator, we enhance propagation by adding, respectively, the global constraints COVERCLOSURE [Schaus et al., 2017] and GENERATOR [Belaid et al., 2019]. After a few preliminary tests, we decided to use smallest item frequency first as variable ordering heuristic and largest value first as value ordering heuristic. We compared CP4MFI to the FPGrowth [Grahne and Zhu, 2003] specialized algorithm for extracting MFIs (Borgelt’s platform: borgelt.net/fpgrowth.html) and CP4MII to WALKY-G [Sthamary et al., 2012] for mining MIIs (CORON platform: coron.loria.fr). We selected several real-sized datasets from the FIMI repository (fimi.ua.ac.be/data). A dataset is characterized by its name, the number of items $|I|$, the number of transactions $|T|$ and its density $\rho$.

5.2 Mining Borders

Our first experiment compares CP4MFI to FP-Growth and CP4MII to WALKY-G for mining MFIs and MIIs. For each approach and each selected instance, Table 2 reports the CPU time and the number of MFIs/MIIs. An instance of a given dataset is characterized by its minimum support $s$ (e.g., Zoo.50 denotes the instance of Zoo with $s = 50$).

A first observation is that the specialized algorithms FP-Growth and WALKY-G follow a completely different approach to extract MFIs and MIIs whereas our CP model can

\footnote{This number is computed by releasing the timeout.}
mine a border or the other just by flipping a parameter. When mining MFIs, the main observation that we can draw from Table 2 is that, as expected, the specialized algorithm FPGROWTH performs very well. However, CP4MI is very competitive too, and even faster on one instance (Chess_160). As for MIIs, CP4MI outperforms WALKY-G in 14 instances out of 26. CP4MI reaches once the timeout of one hour. WALKY-G reaches the timeout on two instances and an out of memory state on three instances. WALKY-G uses a hash structure for storing frequent generators. Maintaining this data structure can be very expensive, especially on dense datasets. For instance, on the very dense Chess_500, WALKY-G exhausts the 8Gb of memory to store the 50M frequent generators. On the moderately dense Connect_7000, WALKY-G needs to store more than 7.4M frequent generators to find the 165K MIIs in 163.25 seconds. On these two instances, CP4MI returns the whole set of MIIs in only 97.42 and 99.42 seconds, respectively. On sparse datasets, where we have few frequent generators, WALKY-G is very efficient. On the very sparse dataset T10, WALKY-G stores less than 50K frequent generators to extract the 698K MIIs of T10_50 in less than 5 seconds whereas CP4MI needs more than 7 minutes.

5.3 Mining Constrained Borders

In many practical applications, the user asks for itemsets satisfying some additional constraints. We performed experiments that show the strength of our CP approach in taking into account user’s constraints. We look for MIIs of minimim size \( lb \) and MIIs of maximum size \( ub \). These two queries can easily be expressed in our CP model by adding the cardinality constraints \( \sum_{i \in I} x_i \geq lb \) to CP4MI, and \( \sum_{i \in I} x_i \leq ub \) to CP4MI. FPGROWTH includes a filtering step allowing us to specify the minimum size of extracted MFIs. However, WALKY-G does not provide such feature, and extracting MIIs under cardinality constraints is only possible via a post-processing step. Table 3 reports the results. We selected the instances having more than one million MFIs and/or MIIs in Table 2. For each selected instance, we increased \( lb \) and we report the CPU time, in seconds, according to the number of solutions.

The main observation on the performance of FPGROWTH for extracting constrained MIIs is that its CPU time is almost constant. For instance, extracting more than 5M or just 10 MFIs on Chess_160 requires almost the same CPU time. This is explained by the fact that the cardinality constraint in FPGROWTH has no pruning power. It is just used as a checker. On the contrary, when \( lb \) increases, CP4MI removes more values thanks to constraint propagation, thus drastically reducing the search space. Take for instance Pumsb_17000. When \( lb = 22 \), CP4MI extracts the 55K MIIs in more than 50 minutes whereas when \( lb \) increases to 30, CP4MI returns the 21 remaining solutions in only 15 seconds. On instances with no solutions, such as Pumsb_17000 with \( lb = 35 \), CP4MI proves the absence of solutions in one second whereas FPGROWTH spends 157.28 seconds.

For WALKY-G, no results are reported because it already has an OOM or TO state before reaching post-processing step. The main observation that we can draw on the behavior of CP4MI is again the strong correlation between the increase of tightness of the cardinality constraint (that is, the decrease of \( ub \)) and the drop in CPU time needed to extract the constrained MIIs. The explanation for this good behavior of CP4MI is again the strength of constraint propagation to discard inconsistent values, thus reducing the search space. On Pumsb_17000, when \( ub \) decreases from 8 down to 1, CP4MI goes from 45 minutes down to 4.59 seconds to return the set of MIIs (1.3M MIIs for \( ub = 8 \) and 2K MIIs for \( ub = 1 \)).

6 Conclusion

We have presented a CP model for mining MFIs and MIIs. We defined two new global constraints, namely FREQUENTSUBS and INFREQUENTSUPERS, with polynomial complete propagators. We have proved that the problem of MFIs or MIIs with constraints is co-NP hard, ruling out the hope for a single CSP solving this problem. Nevertheless, our CP model is sound when the additional constraints are monotone on MFIs or anti-monotone on MIIs. Experiments showed that the CP approach is competitive with state of the art techniques for mining MFIs or MIIs and even better for mining MFIs or MIIs with additional constraints.

Table 2: FPGROWTH vs CP4MI for mining constrained MI and WALKY-G vs CP4MI for mining MI (time in seconds)

Table 3: FPGROWTH vs CP4MI for mining constrained MI and WALKY-G vs CP4MI for mining constrained MIIs (time in seconds)
References


